



▶ Stepper motor controller

9103

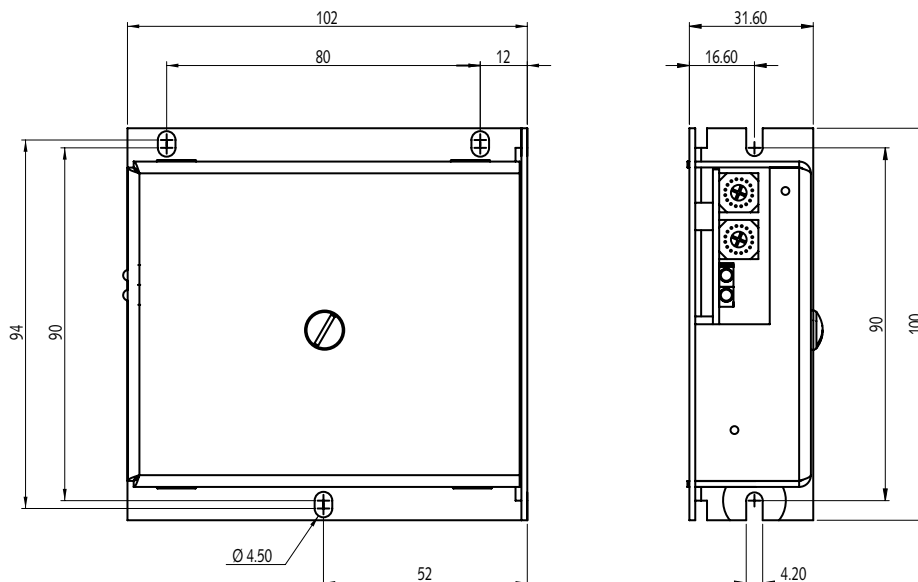


- Adjustable Microstep 1/2 to 1/40
- Adjustable Motor Current ... 0.2 to 4 Aeff
- Interface Pulse
Direction
Boost
Enable
Ready (output)
- Dimensions 100x102x32 mm

- **Compact:** the integration of a powerful microcontroller offers a user-friendly driver with a high degree of flexibility.
- **Interface:** all digital inputs have optocouplers (isolation). Microsteps and motor current are adjustable when the driver is running.
- **High step input frequency:** the driver allows a step frequency up to 200 kHz.
- **High resolution:** the controller drives motor, with 200 steps per revolution, to rotate practically without vibration and with a resolution from 1.8° (full step) to 0.045° (1/40).
- **Intelligent driver:** enable the boost input increases the torque up to 33 % and is particularly useful for acceleration. In order to minimize the temperature rise, the current is automatically reduced to 2/3 of the nominal value at standstill.

▶ Dimensions

Drawing not to scale. All dimensions in mm.



► Technical data

Designation	Value	Unit
Nominal phase current	3.75	A
Max current per phase with Boost	4	A
Motor current selection (Inom)	0.2 ; 0.25 ... 3.75	A
Increment	0.25	A
Boosted current (limited to 4 A max)	133% Inom	-
Reduced current (limited to 0.2 A min)	66% Inom	-
Reduced current delay after last step only available with step selection from 8 to F	100	ms
Power supply: Inom ≤ 2.5 A Inom > 2.5 A	12 ... 40 18 ... 40	V V
Selectable microstep	1/1 ; 1/2 ; 1/4 ; 1/5 ; 1/8 ; 1/10 ; 1/20 ; 1/40	-
Chopper frequency	32	kHz
Maximum step input frequency	200	kHz
Optocoupler inputs for: - motor current on (Enable) - step pulses (Pulse) - direction of rotation (CW/CCW) - motor current boost (Boost)	Typical: 5 16	V mA
Optocoupler output for: - No default (Ready)	Max: 30 10	V mA

► Error detection and diagnosis

State	Ready output	Green LED	Red LED	Current	Restart
No error	1	ON	OFF	Enabled	-
Motor short-circuit	0	OFF	ON	Disabled	No
Maximum step input frequency	0	ON	Blinking	Disabled	Enable = 0
Overtemperature (> 80° C)	0	Blinking	Blinking	Disabled	T < 75° C and Enable = 0
Power supply undervoltage * < 16 Vdc, ** < 11 Vdc	0	Blinking	OFF	Disabled	* > 18 Vdc or ** > 12 Vdc and Enable = 0
Power supply overvoltage (> 45 Vdc)	0	Blinking	ON	Disabled	< 40 Vdc and Enable = 0

* ≤ 2.5 A ** > 2.5 A

Special requirements upon customer specifications. Right to change reserved. Patent protected.

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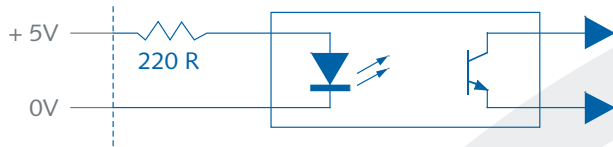
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▶ Electrical Interface

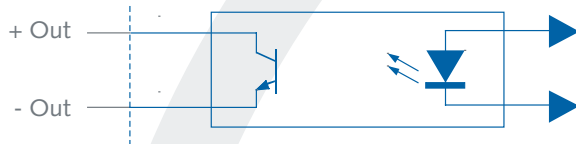
• Inputs

The inputs are compatible with 5 V logic. The increase of logical voltage is allowable up to 24 Vdc when an external resistor is added in order to respect the typical value of the input current.



• Output

The Ready output has an optocoupler link (Open collector). The maximum value is 30 Vdc for the supply and 10 mA for the current.



• Connector pin assignment

Pin N°	Signal	Description
1	VCC +	Supply 12 (18) – 40 Vdc
2	GND	
3	Ready -	No default output
4	Ready +	
5	Boost - (0 V)	Motor current boost input
6	Boost + (5 V)	
7	Enable - (0 V)	Motor current on input
8	Enable + (5 V)	
9	CW/CCW - (0 V)	Direction of rotation input
10	CW/CCW + (5 V)	
11	Pulse - (0 V)	Step pulse input
12	Pulse + (5 V)	
13	Phase B2	Phase B of motor
14	Phase B1	
15	Phase A2	Phase A of motor
16	Phase A1	

▶ Directives & Operating conditions

Operating temperature, $I_{nom} \leq 2$ A	0... 60° C
Operating temperature, $I_{nom} > 2$ A	0... 40° C
Storage temperature	-40... + 125° C
Directives	2002/95/EC (RoHS)

▶ Installation

The cables insulation must withstand at mean 85° C. The cables cross-section must be at mean AWG. The cables between the power supply and the controller, and between the controller and the motor must not be longer than 0.3 m.

▶ Ordering information

Type	Ordering code
9103 standard	9103R002

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