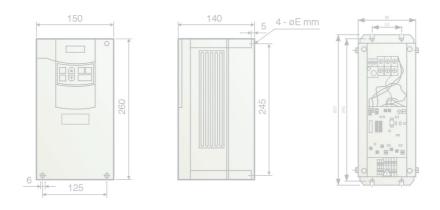


Frequency Inverter



# FR-A 540 EC FR-A 540L-G EC



# **Technical Catalogue**

### The Inverter Generation FR-A 540 (L) EC

# Vektor power for your 3phase AC drive



The FR-A 540 EC is the ideal inverter for very demanding drive applications requiring maximum torque and outstanding smooth running performance. Its comprehensive functions also give this unit a high level of flexibility.

The inverters of the FR-A 540 EC series are available with outputs from 0.4 kW to 55 kW. The higher power range from 75 kW to 530 kW is covered by the inverters of the FR-A 540 L-G EC series.

### **Further Publications within the Factory Automation Range**

# Technical Catalogues

### Technical catalogues FR-E 500, FR-F 500 and FR-S 500

Product catalogue for frequency inverters and accessories of the FR-E 500, FR-F 500 and FR-S 500 series

### **Technical catalogues MELSERVO and Motion Controllers**

Product catalogues for MR-J2 series amplifiers, servo motors and motion controllers with SSCNET connection

### Technical catalogues PLC and HMI

Product catalogues for programmable logic controllers, operator terminals, software, and accessories of the MELSEC PLC series

### **Networks Technical Catalogue**

Product catalogue for Master and Slave modules as well as accessories for the use of programmable logic controllers and frequency inverters in open and MELSEC networks (art. no. 136730)

### **Additional services**

You will find current information on updates, alterations, new items, and technical support on MITSUBISHI ELECTRIC's web pages (www.mitsubishi-automation.com).

The products section of the MITSUBISHI home site includes various documentations of the whole product range by MITSUBISHI ELECTRIC as well as the current version of this catalogue on hand. All manuals and catalogues can be downloaded. The content is updated daily and to date is provided in German and English.

#### About this product catalogue

This catalogue is periodically updated due to product range enlargement, technical changes or new or changed features. Texts, figures and diagrams shown in this product catalogue are intended exclusively for explanation and assistance in planning and ordering the frequency inverter series FR-A 500(L-G) EC and the associated accessories. Only the manuals supplied with the devices are relevant for installation, commissioning and handling of the devices and the accessories. The information given in these manuals must be read before installation and commissioning of the devices or software.

Should questions arise with regard to the planning of devices described in this product catalogue, do not hesitate to contact MITSUBISHI ELECTRIC EUROPE B.V. in Ratingen (Germany) or one of its distributors (see cover page).

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# FREQUENCY INVERTER FR-A 540(L-G) EC

SYSTEM DESCRIPTION	
<ul> <li>Introduction of the FR-A series.</li> <li>Speed/torque characteristics.</li> <li>Equipment and configuration</li> <li>Specifications.</li> <li>Terminal assignment.</li> <li>1</li> </ul>	5 6 8
OPERATION	
◆ Control panel FR-DU04.       1         ◆ Control panel FR-PU04.       1         ◆ VFD setup software.       1	4
PARAMETERS	
◆ Overview of parameters	6
PROTECTIVE FUNCTIONS	
◆ Overview of protective functions       2         ◆ Ressetting methods       2	
APPLICATIONS	
Sample applications	4
Accessories	
<ul> <li>Overview of internal and external options</li> <li>Noise filters</li> <li>Three-phase mains supply chokes</li> <li>Brake units</li> <li>External brake resistors</li> <li>3</li> </ul>	.7 8 9
DIMENSIONS	
◆ Parameter units       3         ◆ Frequency inverters       3         ◆ Filters       3         ◆ Chokes       3         ◆ Brake resistors       4         ◆ Brake units       4	2 7 8 0
APPENDIX	
◆ Order form       4         ◆ Index       4	











### The Frequency Inverter FR-A 540(L-G) EC



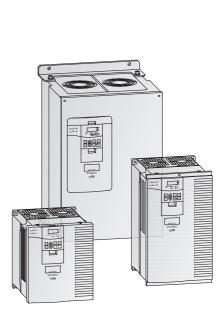
The FR-A 540(L-G) EC is the appropriate inverter for demanding drive tasks with highest requirements for a high torque and excellent frequency precision. Its extensive functions allow flexible applications. The outstanding drive features of the FR-A 540(L-G) EC suit various needs:

- Conveyor technology
- Transport engineering
- Materials-handling technology
- Machining
- Textile machines
- Pumps and ventilating

The FR-A 540 EC inverters are available for a performance range of 0.4 to 55 kW. The higher range of 75 to 530 kW is covered by the inverters of the L series. All devices are designed for the connection to  $3\sim380$  to 480 V (50/60 Hz).

The output frequency ranges from 0.2 to 400 Hz.







# Optimised Drive Characteristics Advanced flux vector control

The original flux vector control developed by MITSUBISHI ELECTRIC offers new performance characteristics in drive technology.

### Precise operation without a PLG

The implemented RISC processor provides an auto tuning of the operating conditions of the motor and thus enables a high-presision operation unaffected by the motor temperature. This technology ensures a stable torque even at ultra low speed.

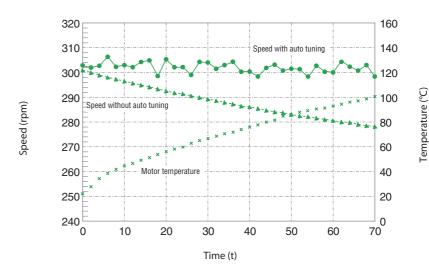
Speed control range: 1:120

The auto tuning of motor data adopts the FR-A 540(L-G) EC inverter perfectly to a broad variety of different motors.

The diagram besides illustrates the temperature/speed characteristics of the online auto tuning function.

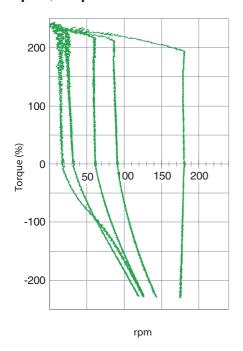


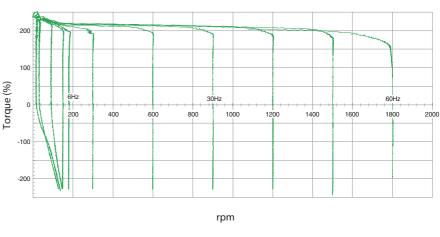
The drive characteristics are even improved in combination with PLG equipped motors (optional FR-A5AP).



Specifications	
Output frequency range	1:1000 (speed control)
Frequency precision	±0.02 % (speed control)
Holding torque	150 % (short-time operation)

### **Speed/Torque Characteristics**





This example shows the speed/torque characteristics at low speed. The magnified view on the left illustrates the operation of

the flux vector control (online auto tuning selected).

# The intelligent Smart Driver Newly developed control

The use of a newly developed ASIC component reduces uneven rotation to less than 50 % (at 1 Hz) of that of the conventional inverters. The status of the main circuit is directly monitored and controlled.

The example below demonstrates the results of this function (inverter operation frequency = 3 Hz / 3.7 kW motor).

### **Highly responsive current limit**

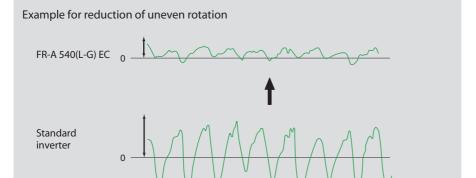
The improvement of the response of the current limiter avoids the unintended occurrence of trips due to overcurrent. Momentary large currents that occur when starting a reverse coasting motor or switching an input contactor etc. no longer trip the current limiter.

### **Extended functionality**

The large functionality range allows a variety of applications for the inverter:

Only a few examples:

- Deceleration function on power failures: Rotary cutters, etc.
- PID control: Air-conditioning, etc.
- Brake sequence function: Conveyor belts, etc.
- Switch-over to commercial power supply: Pumps, etc.



### **Expandability**

Various extension cards are optionally available supporting the direct control by a PLC or a computer.

These options provide additional inputs and outputs such as pulse chain inputs or analog and digital inputs and outputs. Furthermore, several network options facilitate the connection to different open networks.

Refer to page 25 for further details.





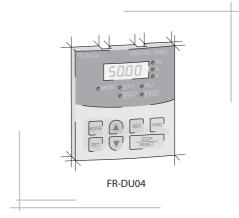
### **User-friendly Operation**

# Easy operation via control panel or

via software

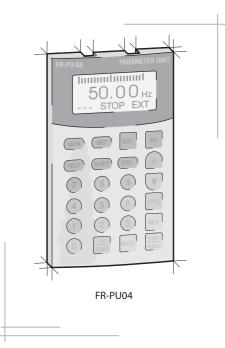
The FR-DU04 control panel is included as standard equipment of all inverters. It features a clear and easy operation of the inverter and displays several operational and alarm signals.. The integrated copy function makes it possible to read out the entire stored parameter set and transfer it to another frequency inverter, or compare the parameters with the settings in the other inverter. The control panel can also be connected remotely via an extension cable.

The FR-PU04 control panel is optionally available. It provides a long-life backlight LC-display. Operational data is directly input on the numeric keypad. Eight different selectable languages are supported on the display. This control panel too can be installed either directly on the inverter or connected remotely with a cable. You can define user groups with which you can activate or change sets of user-definable parameters for specific applications.



The integrated copy function transfers the entire parameter settings to other inverters and thus shortens the initialisation time significantly.

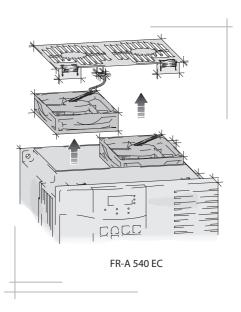
In addition to control panel operation the frequency inverter can also be connected to a standard PC via an RS-485 port and operated from the PC with the optional VFD setup software package. Version 2.4 and above of this package run under Windows 95, 98, Me and XP and also



under Windows® NT and 2000. Using this software you can configure, operate and monitor multiple frequency inverters in a network or directly from a single PC or notebook computer.

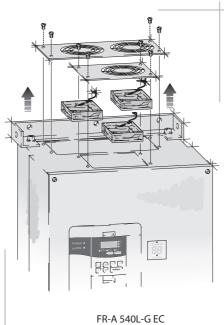
# **User-friendly Maintenance** Easy access to cooling fans

The easily accessable cooling fans can be replaced quickly and easily if required. The lifetime of the cooling fans can be extended significantly through a selective ON/OFF control specified by parameter 244.



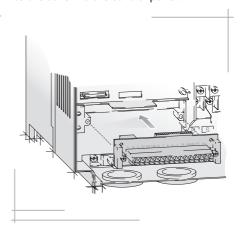
### Easy installation and maintenance

Simple installation and removal of the control terminal block makes installation and maintenance easier



### Easy transfer of parameter settings via control panel

Once the parameter settings are specified, they can be transferred from one inverter to the other via the control panel.



### **Environmentally friendly Operation**

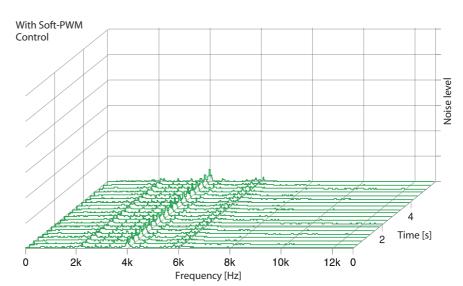
#### **Soft-PWM Control**

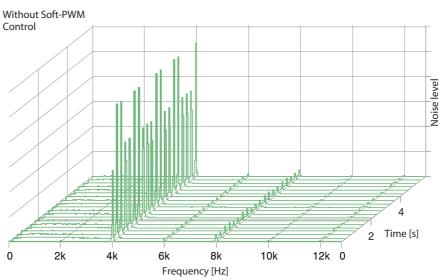
In addition to the conventional low-noise mode, MITSUBISHI ELECTRIC has developed its original Soft-PWM control that suppresses acoustic noise and limits RFI noise to a minimum.

The switchable PWM control facilitates a motor noise silent as whisper even at low carrier frequencies. The diagrams illustrate the difference.

In the upper diagram the frequency components are dispersed: The inverter only generates little noise that might subjectively be compared to the sound of flowing water. The noise does not sound unpleasant.

In the lower diagram the frequency components are concentrated: The inverter generates the typical grating metallic noise.















### **EMC** compatibility

The FR-A 540(L-G) EC inverter regarding its electromagnetic compatibility complies with the European EMC directives, provided it is equipped with an optional EMC filter upon the inputs. The EMC filters are available for inverters of all performance ranges. Refer to page 26 for further details. If necessary you can install line reactors on the input side of the frequency inverters and/or DC link reactors in the link circuit to limit inrush current and reduce the effects of mains fluctuations. The frequency inverters of the FR-A 540L-G EC series include a DC link reactor as standard equipment, and the reactor must be used with these models

### **World-standard specifications**

The units of the FR-A 540(L-G) EC product line are designed to be used world-wide without further effort or certifications.

- World-wide CE, UL, cUL standard compliant
- Selectable sink or source logic.
   The logic for input and output signals can be freely selected. The result is a flexible and easy customisation of the units to the needs of the world market.
- Extended rated input voltage 3~380-480 V; 50 Hz / 60 Hz Tolerance: -15 %: +10 %
- Multiple language parameter unit
- Compatible to several world-wide common communications standards
- MS-Windows compatible world-wide standardised multi-language parameterising software

The FR-A 540(L-G) EC therefore is a world product complying with all relevant standards and easily adopting to the according needs of a country.

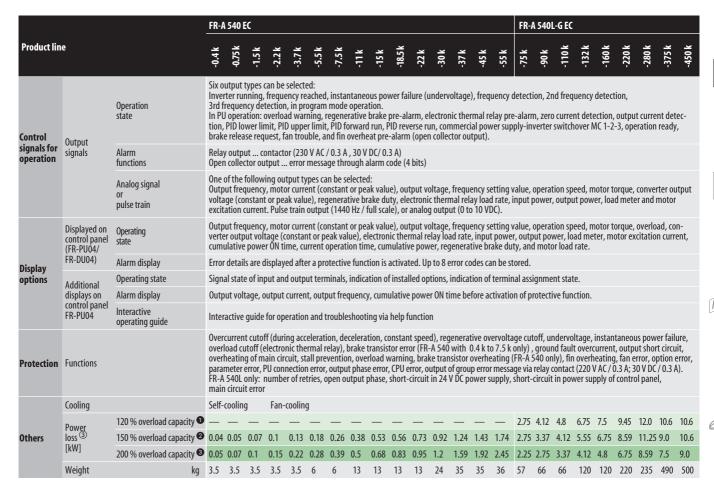
### **Communications**

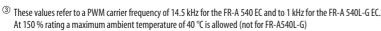
For the integration in an automation plant a serial interface RS485 is included as standard equipment. Through this interface up to 32 inverters can be linked up. Open communications with standardised industrial bus systems as Profibus DP (Europe), Device Net (USA), and CC-Link (Asia) can be realised easily via optional interface cards. This enables the integration of the inverter in entire automation concepts.

# Specifications FR-A 540(L-G) EC

				FR-A	540 E	C													FR-	\ 540L	G EC						
Product lin	e			¥	2 k	¥	¥	¥	¥	¥	<b>×</b>	<b>×</b>	2 k	*	<b>×</b>	*	<b>×</b>	<b>×</b>	<b>×</b>	~	0 k	2 k	0 k	0 k	0 k	5 k	0 k
				-0.4 k	-0.75 k	-1.5 k	-2.2	-3.7	-5.5 k	-7.5 k	-11 k	-15 k	-18.5	-22 k	-30 k	-37	-45 k	-55 k	-75 k	-90 k	-110 k	-132	-160	-220	-280	-375	-450
	Rated	120 % overload capac	ity <b>①</b>	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	132	160	220	250	315	400	530	530
	motor capacity	motor capacity 150 % overload capacity 2		0.75	1.1	2.2	3.0	4.0	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	185	220	280	375	450	530
	[kW] ① · · /	200 % overload capacity 3		0.4	0.75	1.5	2.2	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160	220	280	375	450
		120 % I 120		—	—	_	_	_	_	_	_	_	_	_	_	_	_	_	—	312	362	518	572	732	900	1212	1212
		overload I 110 capacity • I rated		—	—	_	_	_	_	—	_	_	_	_	_	_	_	_	—	286	332	475	525	671	825	1111	1111
		1 rated		_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	260	302	432	477	610		1010	
	Rated	150 %	150	2.7	4.5	7.4	10	14	21	32	44	59	65	81	107	144	162	207	270	324	390	542	648	821		1299	
	current [A] <sup>②</sup>	canacity 2	120 rated		3.6	5.9	8 7	11	17	25	35 29	47	52	65	85	115	130	166	216	259	312			656		1039	
				3	3	4.9	12	9.5	14 24	21 34	46	39 62	43 76	54 86	71 114	96 142	108 172	138 220	180 288	216 360	260 432	361 520	432 650	547 864	722	1444	1010
		200 %		2.3	3.8	6	9	14	18	26	35	47	57	65	86	107	172	165	216		324		488	648		1083	
		canacity 3	rated			4	6	9	12	17	23	31	38	43	57	71	86	110	144	180	216		325		547		
Output	Rated	120 % overlaod capac	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	198	230	329	364		572		
	output	150 % overload capac		1.3	2.3	3.7	5.1	6.9	10.6	16.0	22.1	25.7	32.8	41.1	54.1	73.1	82.3	105	137	165	198	275	329	417	550	660	770
	capacity [kVA]	200 % overload capac	ity 🔞	1.1	1.9	3	4.6	6.9	9.1	13	17.5	23.6	29	32.8	43.4	54	65	84	110	137	165	198	248	329	417	550	660
	Overload	0		120 9	6 of ra	ted m	otor ca	pacity	for 0.5	s; 110	0 % for	1 min	. (max	. ambi	ent te	mpera	ture =	= 40 °C)	); typi	al e.g.	for pu	ımps a	nd fan	S			
	current	0		150 %	6 of ra	ted m	otor ca	pacity	for 0.5	s; 120	0 % for	1 min	. (max	. ambi	ent te	mpera	ture =	= 50 °C)	); typi	cal e.g.	. for pu	ımps, 1	fans ar	nd extr	uders		
	rating	3		200 9	6 of ra	ted m	otor ca	pacity	for 0.5	s; 150	0 % for	1 min	. (max	. ambi	ent te	mpera	ture =	= 50 °C)	); typi	cal e.g.	. for cra	anes a	nd sto	ne brea	akers		
	Voltage			3-pha	00 % of rated motor capacity for 0.5 s; 150 % for 1 min. (max. ambient temperature = 50 °C); typical e.g. for cranes and stone breakers -phase, 0 V up to power supply voltage																						
	Frequency rang	ge	Hz	0.2-4	0.2-400 May 100 0/ / F c. Proking an internal converter supported Futurnal brake unit connectable																						
	Regenerative b	· .			Max. 100 % / 5 s Braking on internal converter supported. External brake unit connectable  Extended flux vector control with online auto tuning of motor data or V/f control																						
	Control method									ine au	to tuni	ing of	motor	data o	r V/f co	ontrol											
	Modulation cor							ft PWA	Λ										/		,						
	Carrier frequen	•	KHZ		0.7 - 14.5 (user adjustable) 0.7 / 1 / 2.5 (user adjustable) up to 5 kHz 3-phase, 380 – 480 V, -15 % / +10 %																						
	Power supply f			50/60 Hz, ±5 %																							
Input	Rated	120 % overload capac	itv 🕦		— —		_	_	_	_	_	_	_	_	_	_	_	_	_	198	230	329	364	465	572	770	770
IIIput	input	150 % overload capac	· _	1.8	3	5.4	6.1	9	14	20	26	36	41	51	66	90	100	126	137	165	198	275	329			660	
	capacity [kVA]	200 % overload capac	· _				5.5	9	12	17	20	28	34	41	52	66	80	100							417		
	Frequency	Analog input				50 Hz (	conne	cting te	ermina	ıl 2: 12		0–10	V; 11 b	oits / 0-	–5 V, c	onnec	ting te	ermina	l 1: 12	bits /-	10 – +	⊦10 V;	11 bit	s / -5 -	- +5 V		
	setting values	Digital input		0.01	Hz / 50	Hz (iı	ncl. pu	se inpi	ıt)																		
	Frequency pred	ision		±0.2 % of max. output frequency (temperature range 25 °C±10 °C) during analog input; ±0.01 % of max. output frequency during digital input																							
	Voltage / frequ	ency characteristics		Base frequency adjustable from 0 to 400 Hz; constant torque or variable torque selectable; optional flexible 5-point V/f characteristics																							
Control	Starting torque	!		150 % / 0.5 Hz (for extended vector control)																							
specifi-		deceleration time		0; 0.1 to 3600 s individual settings																							
cations	Acceleration / o	deceleration characteri	istics					user se																			
	DC braking							g mon -120 H				)—10 s	, volta	ge: 0–	30 % (	adjust	able e	xterna	lly)								
	Torque boost			Manu	al tor	que bo	ost			Ī				-													
	Stall prevention			Respo	nes th	resho	ld 0-2	00 %,	user ac	djusta	ble, als	so via a	nalog	input												0 -15	60 %
	Motor protection			Electr	onic n	notor	orotect	ion rel	ay (rat	ed cur	rrent u	ser adj	ustabl	e)													
	Frequency Analog input			0-5	/ DC, 0	−10 V	DC, 0-	-±10 V	DC, 4	–20 m	ıΑ																
	setting values Digital input			From	contro	ol pan	el or op	otional	circuit	board	ł																
	Starting signal			Starti	ng sig	nal se	f retai	rward ning in	put																		
Control signals for	Speed selection  2nd/3rd acceleration /		,	The c	urrent	speed	can b	can be e chan	selecto ged via	ed (ea a the c	ch spe ontrol	ed can panel	be pre during	eset fro J opera	om 0 to ition.	400 H	Ηz).										
operation	Input signals  2nd/3rd acceleration / deceleration time		/	Accel	eratio		decele	ration 1					lly.														
		JOG operation	n	-				l panel					DC.														
		Current input selection	11					rrent i r outpu	•	-																	
		Output stop Error reset						rm sigi		•		-		prote	ctive f	unctio	n										
		LITOI TESET		1110		arcath	m (aia	ı sıyı	141/13	LJCI V	with th	C 1 C 3 C	or till	- prote	CUVC I	unctio											

① At 150 % rating a maximum ambient temperature of 40 °C is allowed and the PWM carrier frequency must be less than 1 kHz (not for FR-A540L-G) ② The rating 120 % is available with serial marking "type 2" only (shipping from 02.2003).





Due do et line	FR-A 540 EC															
Product line		-0,4 k	-0,75 k	-1,5 k	-2,2 k	-3,7 k	-5,5 k	-7,5 k	-11 k	-15 k	-18,5 k	-22 k	-30 k	-37 k	-45 k	-55 k
Order information	Art. no.	68020	68021	68023	68024	68025	68026	68027	68028	68029	68030	68032	68033	68034	68035	68036
		FR-A 540	DL-G EC (ty	pe E1)												

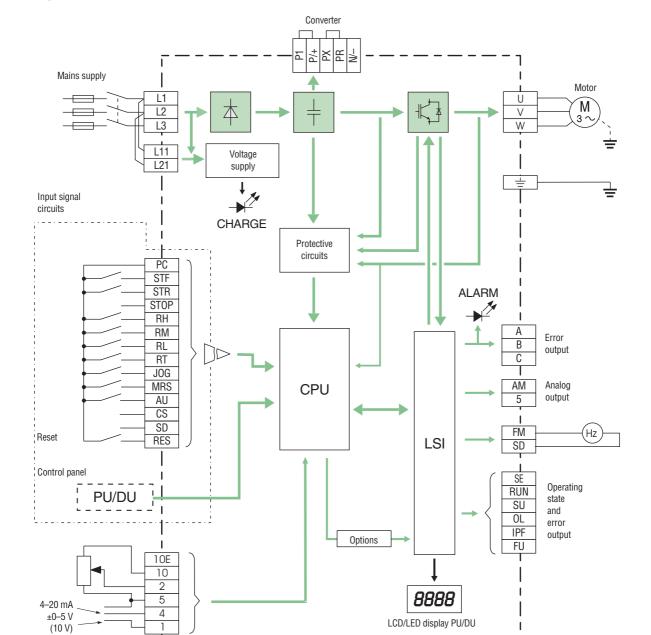
Product line		FR-A 540L-G EC (type E1)										
Productime		-75 k	-90 k	-110 k	-132 k	-160 k	-220 k	-280 k	-375 k	- 450 k		
Order information	Art. no.	141018	141019	141020	141021	141042	141043	141044	142589	142590		

### **General Operating Conditions**

Item	Specifications
Ambient temperature in operation	-10 °C to +50 °C (non-freezing) For selection of the load characteristics with variable torque the max. temperature is 40 °C (not for FR-A 540L-G).
Storage temperature	-20 - +65 °C
Ambient humidity	Max. 90 % RH (non-condensing)
Altitude	Max. 1000 m above NN
Protection rating	Up to 22kW: IP 20 / from on 30 kW: IP00
Shock resistance	10 G (3 times each in 3 directions)
Vibration resistance	2 G: resistance to vibrations from 10 to 55 Hz for 2 hours along all 3 axes
Ambience conditions	For indoor use only, avoid environments containing corrosive gases, install in a dust-free location.
Certifications	UL/CSA/CE/EN

# **Block diagram**





# **Terminal Assignment of Main Circuit Terminals**

Function	Terminal	Terminal name	Description
	L1, L2, L3	Mains supply connection	Mains power supply of the inverter (380–480 V AC, 50/60 Hz)
	P/+, N/-	External brake unit connection	An external brake unit can be connected to the terminals P/+ and N/
	P/+, PR	Optional external brake resistor connection	An optional external brake resistor can be connected to the terminals P/ $+$ and PR. Disconnect the jumper from terminals PR and PX before (FR-A 540-0,4 k to 7,5 k only).
Main circuit	P1, P/+ (P0, P1)	Converter choke coil connection	An optional choke coil can be connected to the terminals P1 and P/+, (for inverters from 375 k to 450 k between P0 and P1). For all FR-A 540L-G inverters the supplied choke coil has to be installed to the mentioned terminals.
	U, V, W	Motor connection	Voltage output of the inverter (3-phase, 0 V up to power supply voltage, 0.2—400 Hz)
	L11, L21	Control circuit mains supply connection	Mains power supply input for a separate supply of the control circuit
	÷	PE	Protective earth connection of inverter

# **Terminal Asssignment of Signal Terminals**

Function	Terminal	Terminal name	Description
	STF	Forward rotation start	The motor rotates forward, if a signal is applied to terminal STF
	STR	Reverse rotation start	The motor rotates reverse, if a signal is applied to terminal STR
	STOP	Start self-retaining selection	The start signals are self-retaining, if a signal is applied to terminal STOP
	RH, RM, RL	Multi-speed selection	Preset of 15 different output frequencies
Control	JOG	JOG mode selection	The JOG mode is selected, if a signal is applied to terminal JOG (factory setting). The inverters FR-A 540L-G 375 k and 450 k are not equipped with a JOG terminal. The start signals STF and STR determine the rotation direction.
connection	RT	Second parameter settings	A second set of parameter settings is selected, if a signal is applied to terminal RT.
	MRS	Output stop	The inverter lock stops the output frequency without regard to the delay time. By changing a parameter the pulsed voltage of the DC braking is output as long as the inverter lock is active.
	RES	RESET input	An activated protective circuit is reset, if a signal is applied to the terminal RES ( $t > 0.1$ s).
	AU	Current input selection	Only, if the AU signal is ON, the inverter can be operated with the 4–20 mA frequency setting signal.
	CS	Automatic restart after power failure selection	The inverter restarts automatically after a power failure, if a signal is applied to the terminal CS.
Common	SD	Common sink for contact input/ reference potential	A determined control function is activated, if the corresponding terminal is connected to the terminal SD. The SD terminal is isolated from the digital circuits via optocouplers.  Reference potential for the pulse output FM. The terminal is isolated from the reference potential of the control circuit.  Common reference potential for 24 V DC/0.1 A output (PC terminal).
	PC	24 V DC output	24 V DC/0.1 A output. Internal power supply source logic.
	10 E	Voltage output for	Output voltage 10 V DC. Max. output current 10 mA. Recommended potentiometer: 1 k $\Omega$ , linear
	10	potentiometer	Output voltage 5 V DC. Max. output current 10 mA. Recommended potentiometer: 1 k $\Omega$ , linear
Setting value	2	Input for frequency setting value signal	The voltage setting value $0-5$ (10) V is applied to this terminal. The voltage range is preset to $0-5$ V. The input resistance is $10$ k $\Omega$ .
specification	5	Reference point for frequency setting value signal	Terminal 5 is the reference point for all analog setting values and for the analog output signal AM. The terminal is not isolated from the reference potential of the control circuit and <b>must not be earthed</b> .
	1	Auxiliary input for frequency setting value signal 0—±5 (10) V DC	An additional voltage setting value signal of $0-\pm 5$ (10) V DC can be applied to terminal 1. The voltage range is preset to $0-\pm 10$ V DC. The input resistance is $10$ k $\Omega$ .
	4	Input for current setting value signal DC 4—20 mA	The current setting value signal (DC 0/4–20 mA) is applied to this terminal. The input resistance is $250\Omega$ .
	A, B, C	Potential free alarm output	The alarm is output via relay contacts. The block diagram shows the normal operation and voltage free status. If the protective function is activated, the relay picks up. The maximum contact load is $200 \text{ V AC} / 0.3 \text{ A}$ or $30 \text{ V DC} / 0.3 \text{ A}$ .
	RUN	Signal output for motor operation	The output is switched low, if the inverter output frequency is equal to or higher than the starting frequency. The output is switched high, if no frequency is output or the DC brake is in operation.
	SU	Signal output for frequency setting value / current value comparison	The SU output supports a monitoring of frequency setting value and frequency current value. The output is switched low, once the frequency current value (output frequency of the inverter) approaches the frequency setting value (determined by the setting value signal) within a preset range of tolerance.
	IPF	Signal output for instantaneous power failure	The output is switched low for a temporary power failure within a range of 15 ms $\leq$ $t_{\rm IPF}$ $\leq$ 100 ms or for under voltage.
Signal outputs	OL	Signal output for overload alarm	The OL is switched low, if the output current of the inverter exceeds the current limit preset in parameter 22 and the stall prevention is activated. If the output current of the inverter falls below the current limit preset in parameter 22, the signal at the OL output is switched high.
outputs	FU	Signal output for monitoring output frequency	The output is switched low once the output frequency exceeds a value preset in parameter 42 (or 43). Otherwise the FU output is switched high.
	SE	Reference potential for signal outputs	Reference potential for the signals RUN, SU, OL, IPF, and FU. This terminal is isolated from the reference potential of the control circuit P24.
	FM	Pulse output	One of 16 monitoring functions can be selected, e.g. external frequency output. FM and AM output can be used simultaneously. The functions are determined by parameters. Either a moving coil gauge (measuring range: 1 mA) or a pulse counter with an initial setting of 1440 pulses/s at 60 Hz output frequency (internal resistance of load min. 10 k $\Omega$ ).
	AM	Analog output	One of 16 monitoring functions can be selected, e.g. external frequency output. FM and AM output can be used simultaneously. The functions are determined by parameters.  A DC voltmeter can be connected. The max. output voltage is 10 V.
Interface	_	Connection of control panel (RS485)	Communications via RS485 I/O standard: RS485, Multi-Drop operation, max. 19200 Baud



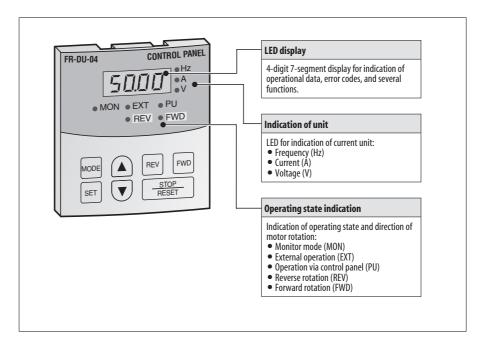
### **Control Panel FR-DU04 (Standard)**

The control panel FR-DU04 is the standard control panel of the inverter FR-A 540(L-G) EC and is included as standard equipment.

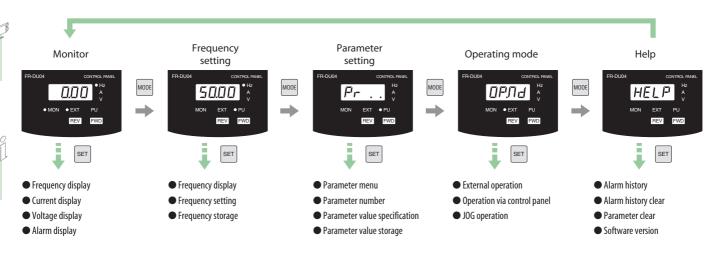
The control panel supports the input and display of several control variables (parameters) and a monitoring and output of current operational data. The data is displayed on a 4-digit LED display.

Besides a display and setting of parameters all operating states of the inverter and motor can be monitored. Faults are indicated by error codes.

The control panel can alternatively be attached directly on the inverter or via cable connection mounted remotely, e.g. in a control cabinet.



### Menu Guide to the Control Panel FR-DU04



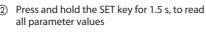
### **Copying parameters**

Via the control panel parameters can be transferred from one inverter to another. For that purpose first read out the parameter settings from the source inverter, then connect the control panel to the destination inverter and transfer the parameters. Inititalising and setting times are reduced significantly that way.

The example besides illustrates the procedure of copying parameters via the control panel FR-DU04.

① Press the MODE key twice and the ▼ key twice





③ Press the ▲ key, then press and hold the

destination inverter

SET key for 1.5 s, to write all values to the

r 002

SET

SET

1,5 s

Press the ▲ key, then press and hold the SET key for 1.5 s, to verify values





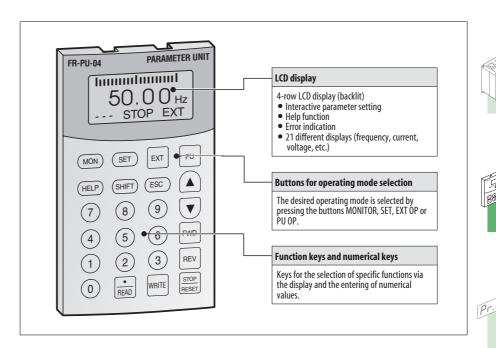
### **Control Panel FR-PU04 (Optional)**

The control panel FR-PU04 with extended functions is available as optional accessory. This control panel provides a 10-key keypad for a direct entering of numerical values. A 4-row LC display returns operational data, parameter names or status and error messages in uncoded text. The control panel displays text in the following selectable languages: English, German, French, Spanish, Swedish, Italian, Finnish, and Japanese. In addition to the functions of the standard control panel the FR-PU04 dis-

The control unit FR-PU04 is used instead of the standard control unit FR-DU04 and can be replaced by this after use.

plays and monitors 21 different values

and states in total.



### Menu Guide to the Control Panel FR-PU04

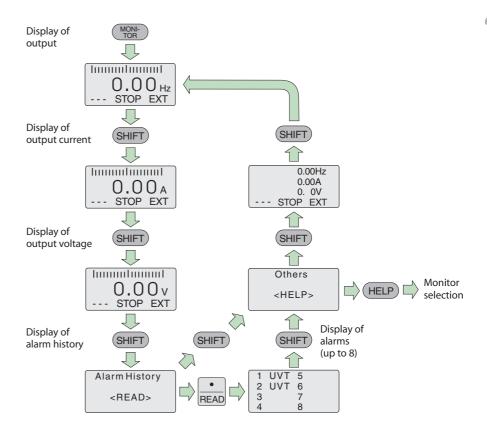
### Displaying the parameter list

Press the SET key to enter the parameter setting menu. Then press the HELP key to display the parameter lists. After pressing the READ key, the according parameter value will be read in.

### **Copying parameters**

Press the SET key and then the  $\triangle$  key to enter the copy mode. Now you find three choices:

- Press the READ key to read out all parameters from the inverter.
- Press the WRITE key to write parameters to the inverter.
- Press the ▼ key to verify the values stored in the control panel and the inverter.





### **Operating Modes**

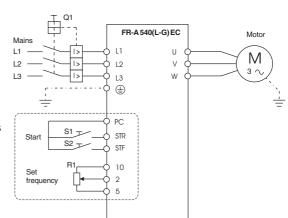


The inverter can alternatively be operated via external signals or directly via the control panels FR-DU04 or FR-PU04.

The operating mode on the control panel FR-DU04 is selected in the operating mode menu or on the control panel FR-PU04 by pressing the EXT OP key for external signal operation and PU OP for control panel operation.

# Sample connection

These connections are required for combined operation or operation by external signals.





### Operation from the control panel

The direction of rotation and frequency setting of the inverter are controlled from the control panel.

The setting of the output frequency is increased or decreased via the ▲ and ▼ The example below shows the operational steps for a frequency setting with following motor start and motor stop.

### Operation by external signals

The direction of rotation and frequency setting of the inverter are controlled by external signals. The following figure shows the display on the control panel FR-DU04 for forward rotation of the motor and a frequency of 50 Hz.



1) Press the MODE key





② Set frequency with SET key























### **Combined operation**

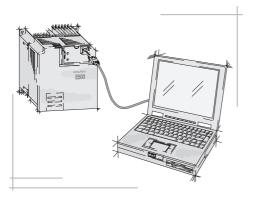
In addition to the operation by external signals and the operation from the control panel (FR-DU04 / FR-PU04) the inverter can be operated in combined operation mode.

- Setting value preset from the control panel and external starting signal.
- External setting value signal and starting signal from the control panel.

### **VFD Setup Software**

The VFD Setup Software is a powerful tool for the operation of your frequency inverter. The software (version 2.4) is MS Windows 95/98/XP and NT/2000 compatible, and therefore allows the inverter operation via any conventional personal computer. Several frequency inverters can be set up, operated, and monitored simultaneously across a network or via a personal computer or notebook. The software is designed for all frequency inverters of the MITSUBISHI FR-A 500, FR-E 500, FR-F 500 and FR-S 500 series.

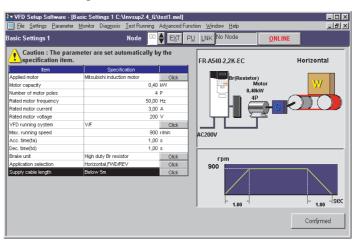
The connection between personal computer and inverter is established either via an RS485 network or directly via an SC-FR PC adapter cable available separately.



### **Benefits**

- System settings
   Due to the network capabilities of the inverter up to 32 frequency inverters can be operated simultaneously.
- Parameter settings
   By means of overall and function related overviews different parameters can be adjusted easily.
- Display functions
   The comprehensible display functions enable data, analog, oscillograph, and alarm displays.
- Diagnostis
   The analysis of the inverter status provides a thorough error correction.
- Test operation
   The test operation provides a simulation of the operation and adjustment via the auto-tuning function.
- File management
   Parameters can be saved on the personal computer and printed out.
- Help The extensive online help provides support concerning all questions regarding settings and operation.

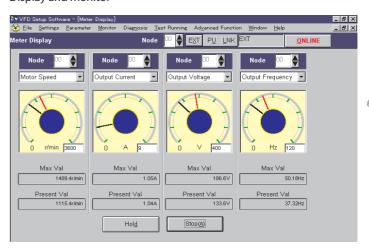
### Parameter setting



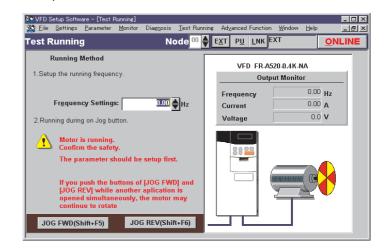




### Display and monitor



# Test operation



# **Parameter Overview**

Function	Parameter	Meaning	Setting		Default	
			FR-A 540 EC	FR-A 540L-G EC	FR-A 540 EC	FR-A 540L-G EC
	0	Torque boost (manual) ① ⑧	0-3		6%/4%/3%/2%®	1%
	1	Maximum output frequency	0-120 Hz	0-60 Hz	120 Hz	60 Hz
	2	Minimum output frequency	0-12		0 F	
	3	V/f characteristics (base frequency)	0-40		50	
Basic	4	1. Multispeed (high) preset - RH ®	0-40		601	
parameters	5	2. Multispeed (high) preset - RM ①	0-40		301	
	6	3. Multispeed (high) preset - RL ®	0-40		101	
	7	Acceleration time	0-360 s /		5 s / 15 s <sup>⑤</sup>	15 s
	8	Deceleration time	0-360 s /		5 s / 15 s <sup>⑤</sup>	15 s
	9	Electronic thermal overload relay (motor protection)	0-500 A	0–3600 A	Rated c	urrent
	10	DC injection brake (initial frequency)	0-120 H	z / 9999	31	
	11	DC injection brake (operation time)	0-10 s	/ 8888	0.5	
	12	DC injection brake (voltage)	0-3	0 %	4%/2% ⑤	1%
	13	Starting frequency	0-6	0 Hz	0.5	Hz
	14	Selection of load pattern <sup>①</sup>	0-	-5	0	
	15	JOG frequency	0-40	00 Hz	5 H	z
	16	JOG acceleration and deceleration time	0-360 s /	0-3600 s	0.5	S
	17	MRS input selection	0,	/2	0	
	18	High-speed max. frequency	120-400 Hz	0-400 Hz	120 Hz	60 Hz
	19	Max. output voltage ①	0-1000 V /	8888 / 9999	888	38
	20	Acceleration / deceleration reference frequency	1-40	00 Hz	50	Hz
	21	Acceleration / deceleration time increments	0,	/1	0	
	22	Stall prevention operation level $^{\textcircled{T}}$	0-200 9	6 / 9999	150 %	150 % (M = const 120 % (M $\sim$ n <sup>2</sup> )
Parameters for tandard drive	23	Stall prevention operation at double speed	0-200 %	6 / 9999	999	9
peration	24	4. Multispeed preset <sup>⑦</sup>	0-400 H	z / 9999	999	9
	25	5. Multispeed preset <sup>⑦</sup>	0-400 H	z / 9999	999	9
	26	6. Multispeed preset <sup>⑦</sup>	0-400 H	z / 9999	999	9
	27	7. Multispeed preset <sup>⑦</sup>	0-400 H	z / 9999	999	9
	28	Multispeed input compensation	0 /	1	0	
	29	Acceleration / deceleration pattern	0/1/	/2/3	0	
	30	Regenerative function selection	0/1	1/2	0	
	31	Frequency jump 1A	0-400 H	z / 9999	999	9
	32	Frequency jump 1B	0-400 H	z / 9999	999	9
	33	Frequency jump 2A	0-400 H	z / 9999	999	9
	34	Frequency jump 2B	0-400 H	z / 9999	999	9
	35	Frequency jump 3A	0-400 H	z / 9999	999	9
	36	Frequency jump 3B	0-400 H	z / 9999	999	9
	37	Speed display	0,1-	9998	0	
	41	Setting value / current value comparison (SU output)	0-10	00 %	10	%
ettings of	42	Output frequency monitoring (FU output)	0-40	00 Hz	6 H	Iz
ontrol outputs	43	Output frequency monitoring / reverse rotation	0-400 H		999	9
	44	2. Acceleration / deceleration	0-360 s /	0-3600 s	5:	5
	45	2. Deceleration time	0-360 s / 0-		999	19
	46	2. Manual torque boost <sup>①</sup>	0-30 %		999	
nd parameter	47	2. V/f characteristics (base frequency) ①	0-400 H		999	
ettings	48	2. Stall prevention operation current	0-20		150 %	150 % (M = const 120 % (M ~ n <sup>2</sup> ) (M
	49	2. Stall prevention operation frequency	0-400 H	z / 9999	0 H	
	50	2. Output frequency monitoring	0-40		30	

				7 12000	Default	cotting
Function	Parameter	Meaning	Setting FR-A 540 EC	g range FR-A 540L-G EC	Perauit FR-A 540 EC	setting FR-A 540L-G EC
	52	LCD main display on control panel ®		20 / 23 / 24 / 25 / 100	FR-A 340 EC	
	53	Bar graph in LCD display ®		4/17/18	1	
isplay	54	FM terminal function selection ®	1–3 / 5–14 /		1	
ınctions	55	Frequency monitoring reference ®		00 Hz	50	
	56	External current monitoring reference ®	0-500 A	0-3600 A	Rated c	
	57	Restart coasting time after power failure	0-5 s / 9999	0-30 s / 9999	999	
estart	58	Restart cushion time before automatic synchronisation		60 s	1	
ux. functions	59	Selection of digital motor potentiometer		1/2		
ax. fulletions	60	Intelligent mode selection	0-		0	
	61	Rated current for intelligent mode	0-500 A / 9999	0-3600 A / 9999	999	
	62	Current limit for intelligent mode (acceleration)		% / 9999	999	
	63	Current limit for intelligent mode (deceleration)		% / 9999	999	
	64	Starting frequency for vertical applications in intelligent mode	0-10 H		999	
	65	Selection of protective function for automatic restart		-5	0	
	66	Starting frequency for stall prevention at boost frequency		00 Hz	50	
	67	Number of restart retries		101–110	0	
	68	Waiting time for automatic restart retry		10 s	1	
	69	Counting of automatic restart retries		)	0	
peration ettings	70	Regenerative brake duty	0-15 % / 0-30 % <sup>⑤</sup>	0-100 %	09	
	71	Motor selection		13–18	0	
	72	PWM function ®	0-87	0-5	2	1
	73			10–15	1	1
	73	Specification of setting value input data Setting value signal filter		-8	1	
	75	Reset condition / connection error / stop ®	0-3 / 14-17	0-3/14-17/100-117	14	1
		Coded alarm output			0	
	76	Write protection for parameters ®		/2/3	0	
	77 78	Prevention of reverse rotation		1/2	0	
					0	
	79	Operation mode selection		-8 0-3600 kW / 9999		
	80	Rated motor capacity for flux vector control	0.4–55 kW / 9999		999	
	81	Number of motor poles for flux vector control  Motor excitation current <sup>③</sup>		14 /16 /9999	999	
	82			9999	999	
	83	Rated voltage of motor for auto-tuning	0-10		400	
	84	Rated motor frequency		Hz / 9999	50	
otor	89	Speed control gain	0-2		100	
onstants	90	Motor constant A ③		9999	999	
	91	Motor constant B ③		9999	999	
	92	Motor constant C ③		9999	999	
	93	Motor constant D ③		9999	999	
	94	Motor constant E <sup>③</sup>		9999	999	
	95	Online auto-tuning selection		/1	0	
	96	Auto-tuning setting / status	0/1		0	
	100	V/f1 frequency ①		lz / 9999	999	
	101	V/f1 frequency voltage ①		000 V	0	
	102	V/f2 frequency ①		lz / 9999	999	
	103	V/f2 frequency voltage ①		000 V	0	
F 5 points	104	V/f3 frequency ①		lz / 9999	999	
djustable	105	V/f3 frequency voltage ①		000 V	0	
	106	V/f4 frequency ①		lz / 9999	999	
	107	V/f4 frequency voltage ①		V 000	0	
	108	V/f5 frequency ①		lz / 9999	999	
	109	V/f5 frequency voltage ①	0-10	000 V	0	



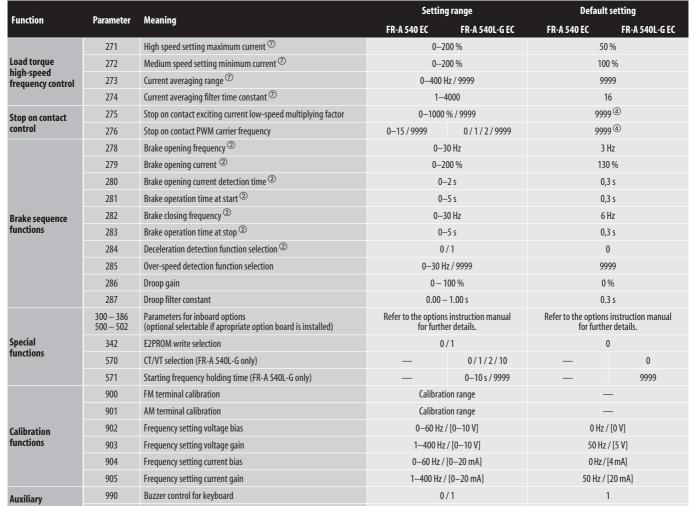
Function	Parameter	Meaning	Setting range	Default setting		
i unction	i didilietei	meaning	FR-A 540 EC FR-A 540L-G EC	FR-A 540 EC FR-A 540L-G EC		
	110	3. acceleration / deceleration time	0-360 s / 0-3600 s / 9999	9999		
	111	3rd deceleration time	0-360 s / 0-3600 s / 9999	9999		
	112	3rd torque boost <sup>①</sup>	0-30 % / 9999	9999		
3rd parameter	113	3rd V/F (base frequency) <sup>¹</sup>	0-400 Hz / 9999	9999		
settings	114	3rd stall prevention operation current	0-200 %	150 % (M = const 120 % (M ~ n <sup>2</sup> ) (W		
	115	3rd stall prevention operation frequency	0-400 Hz	0		
	116	3rd output frequency detection	0-400 Hz / 9999	9999		
	117	Station number	0–31	0		
	118	Communication speed	48 / 96 / 192	192		
	119	Stop bit length/data length	0 / 1 data length 8; 10 / 11 data length 7	1		
ommunications	120	Parity check presence/absence	0/1/2	2		
unctions	121	Number of communication retries	0-10 / 9999	1		
	122	Communication check time interval	0-999.8 s / 9999	9999		
	123	Wait time setting	0-150 ms / 9999	9999		
	124	CR / LF absence/presence selection	0/1/2	1		
	128	PID action selection	10 / 11 / 20 / 21	10		
	129	PID proportional band	0.1–1000 % / 9999	100 %		
	130	PID integral time	0.1-3600 s / 9999	1s		
PID control	131	Upper limit for actual value	0-100 % / 9999	9999		
	132	Lower limit for actual value	0-100 % / 9999	9999		
	133	PID action set point via parameter	0–100 %	0 %		
	134	PID differential time	0,01-10,00 s / 9999	9999		
	135	Selection of outputs for switchover MCs	0/1	0		
	136	MC switchover interlock time	0-100 s	1s		
Commercial Dower supply	137	Start waiting time	0-100 s	0.5 s		
witchover	138	Selection of MCs on alarm message	0/1	0		
	139	Response frequency of MCs	0-60 Hz / 9999	9999		
	140	Backlash acceleration stopping frequency <sup>®</sup>	0-400 Hz	1 Hz		
	141	Backlash acceleration stopping time <sup>(6)</sup>	0–360 s	0.5 s		
Backlash	142	Backlash deceleration stopping frequency <sup>(6)</sup>	0–400 Hz	1 Hz		
	143	Backlash deceleration stopping time <sup>(6)</sup>	0–360 s	0.5 s		
	144	Speed setting switchover	0/2/4/6/8/10/102/104/106/108/110	4		
Display	145	Language selection	0-7	1		
Auxiliary	148	Stall prevention level at 0 V input	0–200 %	150 % (M = const 120 % (M $\sim$ n <sup>2</sup> )		
unctions	149	Stall prevention level at 10 V input	0-200 %	200 % (M = cons 150 % (M $\sim$ n <sup>2</sup> )		
	150	Output current detection level	0–200 %	150 % (M = const 120 % (M $\sim$ n <sup>2</sup> )		
urrent detection	151	Output current detection period	0-10 s	0		
	152	Zero current detection level	0-200 %	5 %		
	153	Zero current detection period	0-1 s	0.5 s		
	154	Voltage reduction selection during stall prevention operation	0/1	1		
	155	RT activated condition	0 / 10	0		
lelp functions	156	Stall prevention operation selection	0-31 / 100 / 101	0		
	157	OL signal waiting time	0-25 s / 9999	0		
	158	AM terminal function selection	1-3/5-14/17/18/21	1		
Aux. function	160	User group read selection ⑦	0/1/10/11	0		

			Catting yangs	Dofoult cotting		
Function	Parameter	Meaning	Setting range	Default setting		
	162	Automatic restart after instantaneous failure selection	FR-A 540 EC FR-A 540L-G EC	FR-A 540 EC FR-A 540L-G EC		
	163	First cushion time for restart	0/1/2 0–20 s	0 0 s		
Restart	164	First cushion voltage for restart	0-100%	0%		
		·		150 % (M — const.)		
	165	Restart stall prevention operation level	0–200 %	150 % (M = $\frac{150}{120}$ % (M $\sim$ $\frac{150}{12$		
nitial monitor	170	Watt-hour meter clear	0	0		
inclui monicoi	171	Actual operationhour meter clear	0	0		
	173	User group 1 registration	0–999	0		
Jser functions	174	User group 1 deletion	0-999 / 9999	0		
Jer ranctions	175	User group 2 registration	0–999	0		
	176	User group 2 deletion	0-999 / 9999	0		
	180	RL terminal function selection	0-99 / 9999	0		
	181	RM terminal function selection	0-99 / 9999	1		
	182	RH terminal function selection	0-99 / 9999	2		
	183	RT terminal function selection	0-99 / 9999	3		
	184	AU terminal function selection	0-99 / 9999	4		
erminal	185	JOG terminal function selection	0-99 / 9999	5		
unction election	186	CS terminal function selection	0-99 / 9999	6		
election	190	RUN terminal function selection	0-199 / 9999	0		
	191	SU terminal function selection	0-199 / 9999	1		
	192	IPF terminal function selection	0-199 / 9999	2		
	193	OL terminal function selection	0-199 / 9999	3		
	194	FU terminal function selection	0-199 / 9999	4		
	195	ABC terminal function selection	0-199 / 9999	99		
uxiliary functions	199	User initial value setting	0-999 / 9999	0		
	200	Program minute/second selection	0 / 2: minute, second; 1 / 3 : hour, minute	0		
Program operations	201–230	Program set	0–2: direction of rotation; 0–400 / 9999: frequency; 0–99:59: time	0/9999/0		
	231	Time-of-day setting	0-99:59	0		
	232	Multi-speed setting (speed 8) <sup>⑦</sup>	0-400 Hz, 9999	9999		
	233	Multi-speed setting (speed 9) <sup>⑦</sup>	0-400 Hz, 9999	9999		
	234	Multi-speed setting (speed 10) <sup>⑦</sup>	0-400 Hz, 9999	9999		
lulti-speed	235	Multi-speed setting (speed 11) <sup>⑦</sup>	0-400 Hz, 9999	9999		
perations	236	Multi-speed setting (speed 12) <sup>⑦</sup>	0-400 Hz, 9999	9999		
	237	Multi-speed setting (speed 13) <sup>⑦</sup>	0-400 Hz, 9999	9999		
	238	Multi-speed setting (speed 14) <sup>⑦</sup>	0-400 Hz, 9999	9999		
	239	Multi-speed setting (speed 15) <sup>⑦</sup>	0-400 Hz, 9999	9999		
:lia	240	Soft-PWM setting	0/1	1		
uxiliary functions	244	Cooling fan operation selection	0/1	0		
top functions	250	Stop selection time	0-100 s / 9999	9999		
	251	Output phase failure	0/1	1		
upplementary unctions	252	Gain overlay for setting voltage	0–200 %	50 %		
anction3	253	Offset overlay for setting voltage	0–200 %	150 %		
	261	Power failure stop selection	0/1	0		
	262	Subtraction frequency at deceleration start	0–20 Hz	3 Hz		
ower failure	263	Subtraction starting frequency	0-120 Hz / 9999	50 Hz		
top functions	264	Power failure deceleration time 1	0-3600 s	5 s		
	265	Power failure deceleration time 2	0-3600 / 9999	9999		
	266	Power failure deceleration time switchover frequenc	0-400 Hz	50 Hz		
unction selection	270	Stop on contact/load high speed frequency control selection	0/1/2/3	0		





Pr.01



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### Remarks on the table:

functions

- ① The parameter setting is ignored, if the advanced flux vector control is activated.
- $^{ ext{@}}$  Can only be set, if parameters 80 and 81 do not equal 9999 and parameter 60 is set to the value 7 or 8.
- $^{\scriptsize \textcircled{3}}$  Can only be accessed, if parameters 80 and 81 do not equal 9999 and parameter 270 is set to the value 801.
- <sup>(4)</sup> Can only be accessed, if parameters 80 and 81 do not equal 9999 and parameter 270 is set to the value 1 or 3.
- $\ensuremath{{\mathfrak S}}$  The setting values depend on the corresponding capacity class of inverter.
- <sup>(6)</sup> Can only be accessed, if parameter 29 is set to the value 3.
- $^{\odot}$  Can even be set even if the inverter is running and if parameter 77 is set to the value 0.
- ® The setting values depend on the corresponding capacity class of inverter. Sub-division of capacity classes: (0.4) / (1.5 3.7 k) / (5.5 k 7.5 k) / (11 k)
- <sup>⑤</sup> The setting values depend on the corresponding capacity class of inverter. Sub-division of capacity classes: (0.4 1.5 k) / (2.2 7.5 k) / (≥11 k)

Calibration for the LC display of the parameter unit

<sup>10</sup> The setting depends on the value of parameter 570.

53

### **Protective Functions Overview**

The inverter FR-A 540(L-G) EC provides a large number of protective functions that protect the drive and the inverter against damage in case of any malfunction.

If an error occurs, the output of the inverter is suspended and the control panel returns an error message.

Display on control panel FR-DU04  E.OC1 Overcurrent 1 (acceleration)  A) The output current of the inverter has reached or exceeded 200 % of the rated current during a cors sthe main outputs, an of inertia of the load (GDP), ton / deceleration, deceleration, or at constant speed.  B) The temperature of the main circuits of the inverter rises rapidly.  Covercurrent 3 (deceleration)  Covervoltage 1 (acceleration)  Description  A) The output current of the inverter has reached or exceeded 200 % of the rated current during a confirmation of the load (GDP), ton / deceleration time pre an exceeding capacity.  Overheating due to insuffice tive cooling fan or choked has increased highly due to regenerative energy. The overvoltage limit was exceeded during acceleration, deceleration, or at constant speed.  E.OV2 Overvoltage 2 (const. speed)  The converter voltage has increased highly due to regenerative energy. The overvoltage limit was exceeded during acceleration, deceleration, or at constant speed.  An overvoltage in the main vates this protective function.	r a ground fault n exceeding moment too short accelera- esets, restart during ation of a motor with cient cooling (defec- neat sink.
E.OC2 Overcurrent 2 (const. speed)  A) The output current of the inverter has reached or exceeded 200 % of the rated current during across the main outputs, an of inertia of the load (GD <sup>2</sup> ), tion / deceleration time pre a motor cidling phase, opera an exceeding capacity.  E.OC3 Overcurrent 3 (deceleration)  E.OV1 Overvoltage 1 (acceleration)  E.OV2 Overvoltage 2 (const. speed)  The converter voltage has increased highly due to regenerative energy. The overvoltage limit was exceeded during acceleration, deceleration, or at constant speed.  The converter voltage has increased highly due to regenerative energy. The overvoltage limit was exceeded during acceleration, deceleration, or at constant speed.  An overvoltage in the main vates this protective function.	r a ground fault n exceeding moment too short accelera- esets, restart during ation of a motor with cient cooling (defec- neat sink.
A) The output current of the inverter has reached or exceeded 200 % of the rated current during acceleration, deceleration, or at constant speed.  B) The temperature of the main circuits of the inverter rises rapidly.  E.OC3  Overcurrent 3 (deceleration)  Overvoltage 1 (acceleration)  Diamond Covercurrent 3 (deceleration)  E.OV2  Overvoltage 2 (const. speed)  The converter voltage has increased highly due to regenerative energy. The overvoltage limit was exceeded during acceleration, deceleration, or at constant speed.  An overvoltage in the main vates this protective function.	too short accelera- esets, restart during ation of a motor with cient cooling (defec- neat sink.
E.OV1  Overvoltage 1 (acceleration)  E.OV2  Overvoltage 2 (const. speed)  The converter voltage has increased highly due to regenerative energy. The overvoltage limit was exceeded during acceleration, deceleration, or at constant speed.  An overvoltage in the main vates this protective function.	e function is acti-
E.OV2 Overvoltage 2 (const. speed)  The converter voltage has increased highly due to regenerative energy. The overvoltage limit was exceeded during acceleration, deceleration, or at constant speed.  Remedy by increasing the documenting an external brain vates this protective function.  An overvoltage in the main vates this protective function.	
E.OV2  Overvoltage 2 (const. speed)  The converter voltage has increased highly due to regenerative energy. The overvoltage limit was exceeded during acceleration, deceleration, or at constant speed.  Remedy by increasing the connecting an external brain value in the main value of	
Overvoltage 3 vates this protective function	deceleration time of
E.THM Overload (motor) The electronic overload protection for the motor or inverter was activated.  The electronic overload protection switch continually detects the motor current and the output frequency of the inverter. If a self-cooling motor operates over a long period at low speed but high torque, the motor is thermally overloaded and the protective function is activated.  Decrease the motor load to Check whether the perform	
E.THT  Overload (inverter)  If several motors are operated by one inverter the motor protection switch will not operate properly. In this case deactivate the motor protection and replace it by external protection switches.	
E.IPF Instantaneous power failure protection power failure protection power failure stays below 15 ms, the operation is proceeded normally.  The output of the inverter is suspended and the alarm message returned, if the power supply fails for more than 100 ms, the inverter shuts down completely. In this case after restoring the power supply the inverter is in the power ON state. If the power failure stays below 15 ms, the operation is proceeded normally.	
E.UVT Undervoltage  The input voltage of the inverter has fallen below the minimum value. The protective function is activated, if the input voltage falls below the minimum value.  An undervoltage can occur, the mains transformer is no high capacity motor is turned the same mains supply circle.	ot sufficient or if a ed ON connected to
E.FIN Overheating of heat sink In case of an overheating of the heat sink the temperature sensor responds and the inverter is stopped.	e.
Excessive speed deviation detection  Excessive speed deviation detection  Excessive speed deviation detection  The motor speed is increased or decreased due to load, etc. during vector contol which is executed with the FR-ASAP option.  Check vor sudden load charges a contract of the co	nge.
E.ECT <sup>①</sup> Wire break detection The encoder signal is turend off during orinetation, PLG feedback or vector contol which is executed with the FR-A5AP option.	ire break.
FN The cooling fan does not operate according to the setting in parameter 244. Replace cooling fan.	
E.BE The transistor failure  Brake transistor failure  A) The integrated brake transistor does not operate properly.  B) Possibly, a thermal overload occured.  Check the relative operating resistor. In case of thermal external brake resistor or an capacity.	difficulties use an
E.GF Ground failure An overcurrent occured due to a ground failure upon the inverter output (load). Check load connections (m	otor circuit).
E.OHT Activation of an external motor protective switch was activated.  If an external motor protective switch for thermal monitoring is used, this switch can activate the protective function of the inverter.  Check motor load and drive protective function of the inverter.	<u>.</u>
E.OLT  Stall prevention overload  A long lasting excess of the current limit (OL display) shut down the inverter.  Reduce the load. Check the preset values for (parameter 22) and the stal tion (parameter 156).	
E.OPT Error in an optional unit A dedicated inboard option does not operate properly. The protective function is activated, if an internal option is improperly installed or connected.  Check connections and control optional unit.	ll prevention selec-















Display on control panel FR-DU04	Meaning	Description	Remedy
E.OP1 to E.OP3	Option slot alarm	The protective function is activated for a fault (e.g. transmission error) of an internal optional unit.	Check the function settings of the optional unit.
E.PE	Memory error	Error on access of the data memory of the inverter.	Please contact your nearest MITSUBISHI ELECTRIC representative if the error occurs repeatedly.
E.PUE	Control panel connection error	A connection error between inverter and control panel occurred during operation. This alarm is only returned, if parameter 75 is set to "2", "3", "16", or "17".	Check the connection of control panel.
E.RET	Automatic restart retry exceeded	After activation of a protective function the inverter failed to be restarted automatically within the number of retries specified in parameter 67.	Remedy the actual cause of the originary protective function.
E.CPU	CPU error	Scan time of CPU was exceeded.	Restart the inverter. Contact the customer service if the error occurs again.
E. 1 to E. 3	Option fault	The inverter output is stopped if a contact fault occurs at the connector between the inverter and the communication option, or if a fault of the communication option itself, etc. occures	Check the installation and all connections of the option board. Contact the customer service if the error occurs again.
E. 6 E. 7	CPU error	Communication error with the built-in CPU.	Restart the inverter. Contact the customer service if the error occurs again.
E.LF	Open output phase protection	One of the phases (U, V, W) is not connected.	Check the connections.
E.P24	24 V DC power output short circuit	The 24 V DC output at the PC terminal is short circuited.	Eliminate short circuit.
E.CTE	Short circuit in the control panel	The power supply of the control unit is short circuited.	Eliminate short circuit. Check the control panel and the connecting cable.
E.MB1 to E.MB7	Brake sequence error	This function stops the inverter output if a sequence error occurs during the use of the brake sequence function (Pr. 278 to Pr. 285)	Check the parameters 278 to 285.
PS	Inverter was stopped via control panel	STOP key on the control panel was pressed during external operating mode.	Check the parameter 77.
RB	Brake resistor overload	The brake resistor must exchange too much energy.	Increase the brake time.
TH	Load too large? Sudden acceleration?	The load is too large or the operating speed too high.	Reduce the load or the operating speed.
OL	Motor run under over- load? Sudden deceleration? oL: Overvoltage OL: Overcurrent	The load is too large or the brake frequency too high.	Reduce the load or the brake frequency.
Err	Error	CPU error	Please contact your nearest MITSUBISHI ELECTRIC representative if the error occurs repeatedly.
E. 14 <sup>3</sup>	DC circuit short circuited	The inverter output is stopped after a short circuit occured	Remove the short circuit and replace the DC fuse.
		The heat sink of brake unit is overheated	Reduce the load moment or brake frequency; clean the heat sink; replace the cooling fan
		DC fuse is blown	Eliminate the short-circuit and replace the fuse
		The control board is overheated	Replace the cooling fan; check the ambient temperature
E.15 <sup>②</sup>	Main circuit failure	An overcurrent on the output has occured	Eliminate the short-circut or short to ground; replace the motor; increase the brake time; reduce the load fluctuations, increase the acceleration time; check the brake operation
L.13 °	Main circuit failule	Power supply for cooling fan fails	Eliminate the short-circuit; replace the power supply for cooling fan; replace the fuse
		General overcurrent	Eliminate the short-circuit and replace the fuse; eliminate the short-circuit on output or short to ground; replace the motor and reduce the load
		The heat sink is overheated	Clean or replace the heat sink; check the ambient temperature
		A gate power supply failure has occured	Eliminate the short-circuit; replace the gate power supply

 $<sup>^{\</sup>scriptsize\textcircled{1}}$  These error messages are valid only for FR-A 540-0,4k bis -55k EC inverters.

 $<sup>\</sup>ensuremath{@}$  These error messages are valid only for FR-A 540L-G75k bis -280k EC inverters.

 $<sup>\</sup>ensuremath{^{\circlearrowleft}}$  These error messages are valid only for FR-A 540L-G375k and -450k EC inverters.

 $<sup>^{\</sup>textcircled{4}}$  These error messages are valid only for FR-A 540L-G75k bis -450k EC inverters.

### **Resetting Methodes**

When a protective function is activated, the output of the inverter is switched off. The motor coasts to a halt. The output remains switched off until the error cause is eliminated and the inverter reset. The inverter can be reset following three different methods:

- Switch the power supply OFF and ON again.
- Switch the reset signal ON for at least 0.1 s
- Press the RESET key on the control panel.

If the reset signal is ON continuously, the control panel FR-DU04 returns an error message while the control unit FR-PU04 indicates that the reset procedure is in progress.

When a protective function is activated, the control panel FR-DU04 returns an error code as listed in the table above. The control panel FR-PU04 returns error messages in clear.

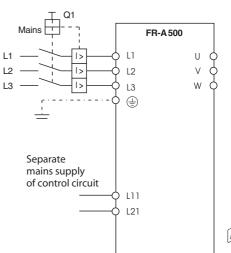
If on occurrence of an error the input protection contactor is toggled the error message cannot be retained, since there is no power supply for the control circuit. If the error message is intended to be retained in spite of an activation of the protectve contactor, the control circuit has to be supplied by a separate power supply.

# Separate power supply for the control circuit

The figure shows the connection of the separate 380-480 V AC (-15%/+10%) power supply for the control circuit. The current consumption is 2 A.

Prior to the connection remove the two short bars upon L1-L11 and L2-L21 on the inverters FR-A540 EC 0.4 k through 3.7 k and the short bars L11 and L21 on the inverters FR-A 540 EC 5.5 k through 55 k and FR-A 540L-G EC.

Please refer to the according manual for a precise description of the connection.

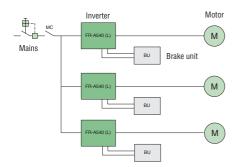








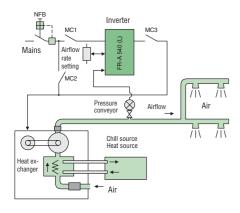
### **Sample Applications**



### High-speed crane or lift

- The wide-range speed control facilitates high-speed control combined with high precision.
- A brake unit is not required because a power regenerating function is provided.
- Since this application comprises vertical and horizontal movements simultaneously the capacity class of the inverter results from the total capacity of both motors.
- The power supply for the mechanical brake is to be connected to the power supply for the converter.
- The mechanical brakes can be applied with optimal timing using the brake sequence function specified via parameters
- The large starting torque allows powerful performance in lifting operations.

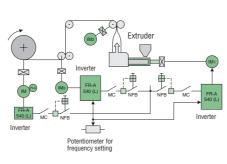
### Air-conditioning fan



- Due to the integrated PID control function the inverter is suitable for constant temperature control functions.
- The timing of the contactors MC1–MC3 is controlled precisely through parameter settings.
- An electromechanical interlock that prevents MC2 and MC3 from being switched ON simultaneously is required.

The inverter controls temperature constantly during operation, creating a pleasant environment and saving energy.

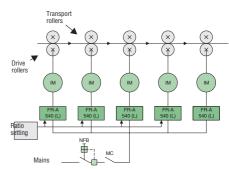
### **Extruder**



- The speed of the motor for the extruder and the motor for the pull-off rollers is set via a potentiometer. The different frequencies of the inverters can be adjusted via bias and gain (PR. 902 and PR. 903) of the input frequency signal.
- The advanced flux vector control with online auto tuning of the motor operating data enables the operation with minimum speed fluctuations. Thus, the pressure of the extruder can be adopted to different materials.

Using a PLG on the wind-up motor allows an even more precise control of operations.

### Wire drawing mill



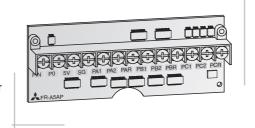
- The advanced flux vector control provides high-precision control of individual motors within a production line.
   Each successive motor is operated at a slightly higher speed.
- The speed of the latter motors must be proportional to the elongation rate resulting from the reduced cross-section of the wire
- When the online auto tuning function is selected, the motor constants are automatically tuned each time the motor starts, eliminating speed variations caused by temperature fluctuations and providing stable control.

### **Overview of Internal and External Options**

A large number of options allows an individual adoption of the inverter to the according task. The options can be installed quickly and easily. Detailed information on installation and functions is included in the manual of the options.

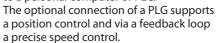
The options can be divided into two major categories:

- internal options
- external options



### **Internal options**

The internal options comprise input and output extensions as well as communications options supporting the operation of the inverter within a network or connected to a personal computer or PLC.





Option			Туре	Description	Remarks / specifications	Art. no.
	12-bit digital i	input	FR-A5AX	Interface for the input of the frequency setting via 3-digit BCD or 12-bit binary code, setting of gain and bias supported.	Input: 24 V DC; 5 mA; open collector or switching signal, sink or source logic	68039
	Digital output			Selectable 7 of 27 standard output signals of the inverter can be output at the open collector.	Output load: 24V DC; 0,1 A, sink or source logic	
	Expansion ana	alog output	FR-A5AY	Selectable 2 of 16 additional signals (e.g. output frequency, output voltage, output current) can be output and indicated at the FM / AM output.  Display on measuring gauge: 20 mA DC or 5 V (10 V) DC	Output: max. $0-10$ V DC; $0-20$ mA; Resolution: $3$ mV at voltage output, $1~\mu$ A at current output, accuracy: $\pm 10~\%$	68040
	Relay output		FR-A5AR	Selectable 3 of 27 standard output signals of the inverter can be output through relay terminals.	Switching load: 230 V AC/0.3 A, 30 V DC/0.3 A	68038
Encoder feedback (PLG) main axis orientation / position control		ntation /	FR-A5AP	This option is used in combination with a pulse encoder for the position control.  The motor speed is detected by a pulse encoder and is fed back for a precise speed control at variable load.  The current position of drive shaft and the current motor speed can be displayed on the control panel.	Terminal for 3-phase asynchronous motors (2 – 8 poles) PLG with differential output (5 V DC)	68037
	Pulse train input		train input The speed can be entered in the inverter via		Input: 24 V DC; 10 mA; open collector, max. 100.000 pulses/s	
Internal options	PIL MONITOR		OI-FR-APTC	The PTC board is a device that is capable to give an overtemperature alarm by detecting the ohmic value of one PTC resistance.	Connection of PTC resistors series KTY	147224
		Computer link	FR-A5NR	Via this additional RS422 or RS485 compatible interface the operation, display functions, and parameter settings can be controlled by a computer (PC etc.).  For minimum noise use twisted pair cables for the connection.	EIA RS485 and RS422, Multi-Drop operation, max. 19.200 Baud; max. 500 m, connection of up to 32 inverters supported	68046
		Profibus/DP	FR-A5NPA	Option board for the integration of a frequency inverter into a Profibus/DP network. The operation, display functions, and parameter settings can be controlled by a computer (PC etc.) or a PLC.	Connection of up to 126 inverters supported. Maximum transfer rate: 12 MBaud	141680
	Communi- cations	DeviceNet <sup>TM</sup>	FR-A5ND	Option board for the integration of a frequency inverter into a DeviceNet. The operation, display functions, and parameter settings can be controlled by a computer (PC etc.) or a PLC.	Maximum transfer rate: 10 MBaud	68043
		CC-Link	FR-A5NC	Option board for the integration of a frequency inverter into a CC-Link network. The operation, display functions, and parameter settings can be controlled by a PLC.	Maximum transfer distance: 1200 m (at 156 x 10 kBaud)	68042
		Modbus Plus	FR-A5NM	The operation, display functions, and parameter settings can be controlled by a computer (PC etc.) or a PLC.	Maximum transfer distance: 100 m (at 10 kBaud)	68044
		CANopen	OI-FR-A5NCO	Option board for the integration of a frequency inverter into a CANopen network. The operation, display functions, and parameter settings can be controlled by a computer (PC etc.) or a PLC.	Maximum transfer rate: 1 MBaud	139377
Accession		nunications card	SioCard	Connection between mobile PC (PCMCIA) and frequency inverter RS485 (RJ45); no external power supply neccessary	Length 3 m; for parametrization and programming of the frequency inverter;	69946
Accessories	Conection cab	le	SC-FR PC	Connection between PC (RS232) and frequency inverte RS485 (RJ45); no external power supply necessary	it can be used for example with the VFD setup software	88426



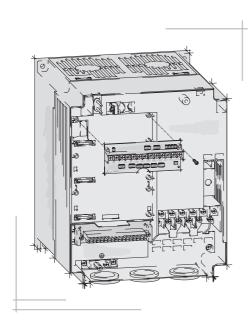
### **External options**

Besides the control panel FR-PU04 that provides an interactive control of the inverter the external options comprise noise

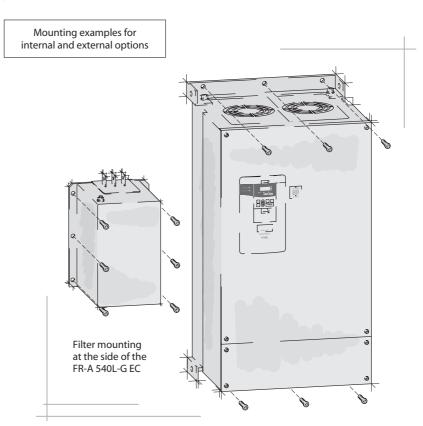
filters complying with the EMC directives, power chokes improving the efficiency as well as brake units and brake resistors.

Option			Туре	Description	Remarks/Specifications	Art. no.	
	Control panel (8 languages)		FR-PU04	Interactive control panel with LCD display.	Refer to p.13 for detailed description	67735	
	Connecting cab	le for control panel	FR-A5 CBL	Cable for a remote connection of the control panel FR-DU04 or FR-PU04.	Available length: 1; 2.5 and 5 m	1 m: 70727 2.5 m: 70728 5 m: 70729	
	Connection cab	le	SC-FR PC	Communications cable for RS232 or RS485 interface to connect an external personal computer	Length 3 m; can be used for example with the VFD setup software	88426	
	VFD setup softv	vare	FR-SW0-SETUP-W□	Parameterization and setup software for the whole FR-A 500 series	English / German	149718	
	EMC FR-A		FFR-□□□	Naire Glass for annulisment with FAAC discations	Defends a 27 for detailed description	27	
	noise filter	FR-A 540L-G	FN 3359-□□□	Noise filter for compliance with EMC directives. Refer to p.27 for detailed description		see p. 27	
External	External brake	FR-A 540 0.4 k bis 7.5 k	FR-ABR-H RUFC	The connection of an external brake resistor improves the brake capacity of the inverter (only for inverters of capacity classes 0.4 to 7.5 k).	Refer to p.30 for detailed description	see p. 30	
options	resistor	FR-A 540L-G	MT-BR 5	To improve the brake capacity of the inverter; is used in combination with a brake unit			
	DC converter	FR-A 540	FR-BEL-(H) □ □	For an increased efficiency and compensation of voltage		,	
	circuit choke coil	FR-A 540L-G	MT-BEL ①	fluctuations.		on request	
	Mains circuit	FR-A 540	FR-BAL-(B)	For an increased efficiency and compensation of voltage	Defends a 20 fem detailed described	20	
	choke coil	FR-A 540L-G	_	fluctuations.	Refer to p.28 for detailed description	see p. 28	
	Brake units	FR-A 540	BU-H15k BU-H30k BU-UFS22 BU-UFS40	For an improvement of the brake capacity. For loads with high moment of inertia or negative loads. Used in combination with a resistor unit.	Refer to p.29 for detailed description	see p. 29	
		FR-A 540L-G	MT-BU 5 BU-UFS110	toi uiit.			

① The DC converter circuit choke coil is standard equipment of the FR-A 540L-G type inverters. This choke coil is required for the operation of the inverter.







### Noise Filters for FR-A 540 / 520



### **Noise filters**

For the compliance of the FR-A 500 series with the EMC directives of the European Community regarding the electromagnetic compatibility, the inverter has to be equipped with a noise filter across the input circuit and has to be installed and wired according to the EMC directives. In order to ensure a proper and safe operation of the componentry follow the points below:

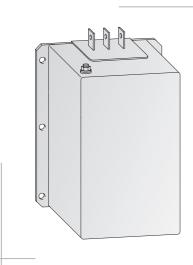
- Ground the filter prior to applying the power supply.
- For the selection of a ground fault protective switch or relay take the leakage current of the filter into account.
- Ensure a perfect grounding of the filter, if you do not intend to use a protective switch or relay across the input circuit.

Filter	Inverter		Power loss	Class	Leakage	Weight	Art. no.
riiter	FR-A540 EC	FR-A 520	[W]	Class	current [mA]	[kg]	Art. IIO.
FFR-A540-8A-SF100	0.4 k-1.5 k	0.4 k/0.75 k	5	A + B*	< 30	1.5	104741
FFR-A540-16A-SF100	2.2 k/3.7 k	1.5 k/ 2.2 k	8	$A + B^*$	<30	1.5	104752
FFR-A540-30A-SF100	5.5 k/7.5 k	3.7 k	14	$A + B^*$	< 30	1.8	104753
FFR-A540-50A-SF100	11 k/15 k	5.5 k	25	$A + B^*$	< 30	3.5	104754
FFR-A540-75A-SF100	18.5 k/22 k	7.5 k/11 k	34	$A + B^*$	< 35	4.1	104755
FFR-A540-95A-SF100	30 k	15 k	36	$A + B^*$	< 35	6.7	104756
FFR-A540-120A-SF100	37 k	18.5 k	34	$A + B^*$	< 35	9.7	151881
FFR-A540-180A-SF100	45 k-55 k	22 k-30 k	62	A + B*	< 35	10.8	104757

<sup>\*</sup> These filters meet the requirements of EN55011A for a motor cable length of 100 m and of EN55022B for a motor cable length of 20 m.



### Noise Filters FR-A 540L-G / FR-A 520



### Noise filters for high capacities

The extremely compact line of FN 3359

The FN 3359 filters are suitable for a noise 011.

00 m (shielded) is possible.

Art. no. 141097 104663

104664

104665

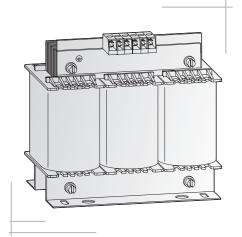
104666 130229

	filters provides the user with an efficient noise suppression at low room requirements.  suppression meetir  For a cable length of the compliance wit						
Filter	Inv	erter	Power loss	Class	Leakage	Weight	
	FR-A 540L-G EC	FR-A 520	[W]		current [mA]	[kg]	
FN 3359/180/99	75 k	37 k	34	Α	< 6	7	
FN 3359/250/99	90 k	45 k	38	Α	< 6	7	
FN 3359/400/99	110 k-132 k	55 k	51	Α	< 6	10.5	
FN 3359/600/99	160 k/220 k	_	65	Α	< 6	11	
FN 3359/1000/99	280 k/375 k	_	84	Α	< 6	18	
FN 3359/1600/99	450 k	_	130	Α	< 6	24	





### **Power Chokes for Three-Phase Current FR-BAL-B-** $\square\square$ k



### Three-phase mains supply chokes

The three-phase mains supply chokes FR-BAL-B-□□k for the frequency inverters FR-A 540 EC compensate voltage fluctuations and simultaneously increase the efficiency.

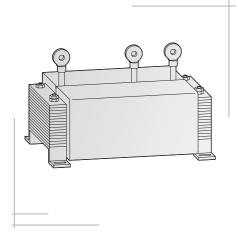
Applying the appropriate power choke an overall efficiency of up to 90 % can be achieved.

The use of a power choke is especially recommended for mains circuits where high capacities are switched, for example, via thyristors.

Inverter	Choke	Power capacity	L [mH]	Current [A]	Power loss [W]	Insolation class	Weight [kg]	Art. no.
	FR-BAL-B-4.0 k	FR-A 540-0.4 k-3.7 k	2.340	12	31	T40/E	3.0	87244
	FR-BAL-B-5.5k	FR-A 540-5.5 k	1.750	16	44	T40/E	3.7	87245
	FR-BAL-B-7.5 k	FR-A 540-7.5 k	1.220	23	59	T40/E	5.5	87246
	FR-BAL-B-11k	FR-A 540-11 k	0.667	42	68	T40/B	10.7	71053
FD A 540	FR-BAL-B-15k	FR-A 540-15 k	0.667	42	68	T40/B	10.7	71053
FR-A 540	FR-BAL-B-22 k	FR-A 540-18.5 k/22 k	0.483	58	77	T40/B	11.2	87247
	FR-BAL-B-30 k	FR-A 540-30 k	0.369	76	86	T40/B	11.6	87248
	FR-BAL-B-37 k	FR-A 540-37 k	0.295	95	113	T40/B	18.6	87249
	FR-BAL-B-45 k	FR-A 540-45 k	0.244	115	118	T40/B	21.4	71054
	FR-BAL-B-55 k	FR-A 540-55 k	0.191	147	120	T40/F	22.6	87250



### ■ DC Reactor for FR-A540L-G



### **DC Link Reactors**

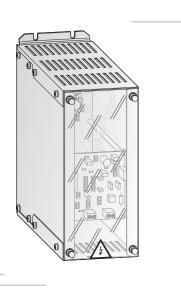
A DC link reactor is included as standard equipment with the FR-A540L-G frequency inverters. This reactor is essential for the operation of the inverter and must be installed.

The function of these reactors corresponds to that of the three-phase mains supply chokes described above.

Application		Power loss [W]		Weight [kg]	Art. no.
(inverter)	at 120 %*	at 150 %*	at 200 %*		AFL. IIO.
FR-A 540L-G 75 k	166	166	125	19	
FR-A 540L-G 90 k	202	192	144	20	
FR-A 540L-G 110 k	210	202	150	22	
FR-A 540L-G 132 k	253	214	168	29	A DC link reactor is included as
FR-A 540L-G 160 k	260	253	202	36	standard equipment with the
FR-A 540L-G 220 k	290	276	239	48	respective frequency inverter.
FR-A 540L-G 280 k	396	372	306	57	
FR-A 540L-G 375 k	530	450	375	100	
FR-A 540L-G 450 k	530	530	450	100	

<sup>\*</sup>Overload capacity

### **■** Brake Units BU-UFS



For a braking torque higher than 20 % or a duty cycle higher than 30 % an external brake unit including the adequate brake resistors has to be installed.

The brake units BU-UFS listed below are cascadable so that the optimum dimensioning can always be achieved.

Suggestions regarding an adequate dimensioning of brake resistors can be found in the operating manual for the brake unit. Like any other documentation of frequency inverters you will find the operating manual on the MITSUBISHI ELECTRIC homepage.

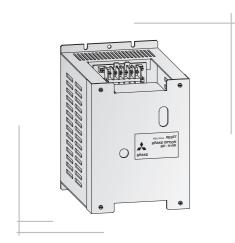


Inverter	Brake unit	Max. peak current [W]	Max. instantane- ous power [kW]	Max. duty cycle [ED]	Art. no.
FR-A 540	BU-UFS22	34	25	10 %	127947
FR-A 540L-G	BU-UFS40	55	41	10 %	127948
FR-A 540L-G	BU-UFS110	140	105	5 %	127950



# Pr.UI

### Brake Units BU and MT-BU



Remove short bar for inverters of the capacity ranges 0.4 to 7.5 k! The inverters among the capacity range of 11 k to 55 k do not include an integrated brake unit. The capacitors in the converter circuit provide a braking torque of approx. 20 % of the rated motor torque (with the inverters from 11 k). If a higher braking torque or for the inverters 0.4 k to 7.5 k a greater duty cycle than 30 % is required, an external brake unit is required.

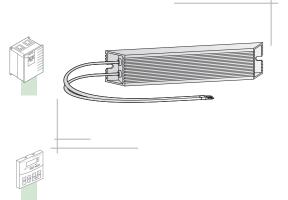
Brake resistors are to be provided application related. Regarding the selection of a suitable brake resistor you should contact MITSUBISHI ELECTRIC. The brake unit and brake resistor are connected according to the connecting diagram below. Prior to the connection of an external brake unit to the inverters 0.4 k to 7.5 k the short bar across terminals PR and PX has to be removed.





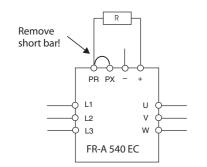
Inverter	Brake unit	Number of required units for inverter	Braking torque	Art. no.
FD A F40	BU-H15k	1 x for 0.4 k–3.7 k; 2 x for 5.5 k–7.5 k	100 %, 30 s	3447
FR-A 540	BU-H30k	1 x for 11 k-15 k; 2 x for 18.5 k-22 k; 3 x for 37 k-45 k; 4 x for 55 k	100 %, 30 s	3446
	MT-BU5-H75 k	1 x MT-BR5-H75 k	100 %, 10 % ED	125700
	MT-BU5-H150 k	2 x MT-BR5-H75 k	100 %, 10 % ED	125701
FR-A 540L-G	MT-BU5-H220 k	3 x MT-BR5-H75 k	100 %, 10 % ED	125702
	MT-BU5-H280 k	4 x MT-BR5-H75 k	100 %, 10 % ED	125703
	MT-BU5-H375 k	5 x MT-BR5-H75 k	100 %, 10 % ED	125705

### **External Brake Resistor FR-ABR-H**□□k and MT-BR

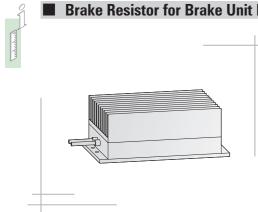


Among the capacity range of 0.4 k to 7.5 k the inverter is equipped with an internal brake chopper and brake resistor as standard. The internal brake resistor is limited to a brake duty of 2 % due to thermal reasons. A higher brake duty is achieved by the use of an external brake resistor with a higher rated capacity. The brake duty is selectable by parameter 70 and can be specified to up to 30 % via parameter 70. The brake resistor MT-BR5 for the frequency inverter FR-A 540 L-G is used exclusively in combination with a brake unit (see page 29).

- Prior to the connection of the external brake resistor remove the short bar across terminals PR and PX, then connect it to terminals PR and +.
- The regenerative brake duty should be set at levels below the permissible brake duty specified in the table.
- Since the temperature of the brake resistor may exceed 300 °C take care to provide a sufficient heat dissipation.



Brake resistor	Regenerative brake duty	Resistance [ $\Omega$ ]	Art. no.
FR-ABR-H0.4 k	10 %	1200	46601
FR-ABR-H0.75 k	10 %	700	46411
FR-ABR-H1.5 k	10 %	350	46603
FR-ABR-H2.2 k	10 %	250	46412
FR-ABR-H3.7 k	10 %	150	46413
FR-ABR-H5.5 k	10 %	110	50045
FR-ABR-H7.5 k	10 %	75	50049
MT-BR5-H75 k (FR-A 540 L only)	6 %	6.5	125699



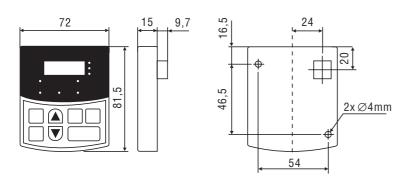
### **Brake Resistor for Brake Unit BU-UFS**

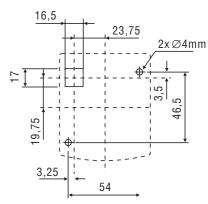
The brake resistors RUFC for the frequency inverters FR-A-540(L-G) EC are designed for the exclusive use in combination with a brake unit BU-UFS.

Please, note the specifications for the allowed duty cycle (ED max.) included in the instruction manual for the brake unit!

Туре	Application	Regenerative brake duty	Resistance $[\Omega]$	Capacity [W]	Art. no.
RUFC15	BU-UFS 15	10 %	1 x 40	1200	129628
RUFC22	BU-UFS 22	10 %	1 x 24	2000	129629
RUFC40 (Set)	BU-UFS 40	10 %	2 x 6,8	2000	129630
RUFC110 (Set)	BU-UFS 110	10 %	4 x 6,8	2000	129631

### Control Panel FR-DU04

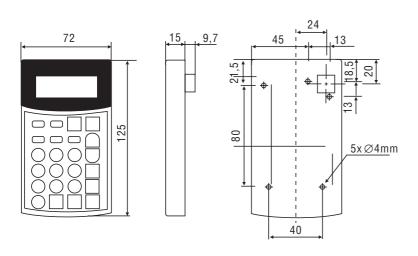


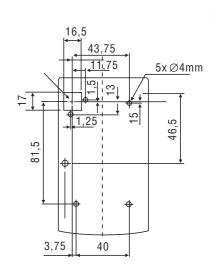




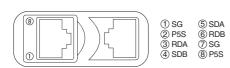
All dimensions in mm

### Control Panel FR-PU04





All dimensions in mm



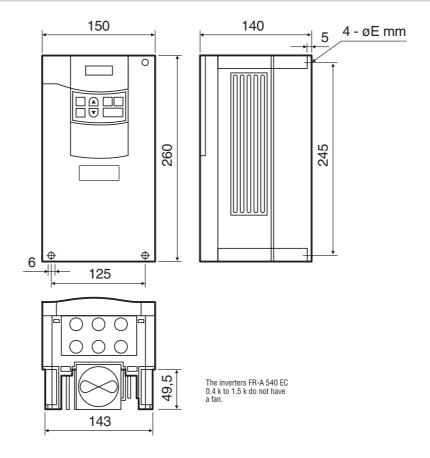
### Connection of the control panel

The control panel can be attached on the inverter after removing the protective cover. The control panel can be connected to the inverter remotely via the connecting cable type FR-A5-CBL (1m; 2.5m; 5m). You must only use the original MITSUBISHI ELECTRIC cable. This cable is available as optional accessory. Plug the cable in the according connectors on the control panel and the inverter.

The figure besides shows the pin assignment of the connector plugs.

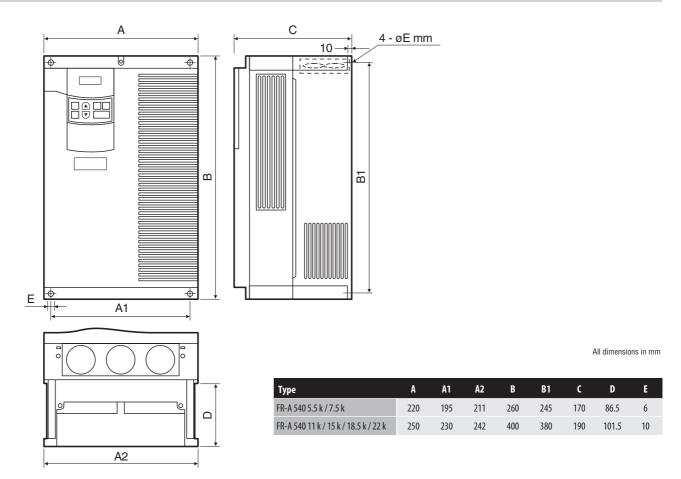
Never connect fax modems or modular telephone plugs with the connectors. Otherwise, the inverter might be damaged. The connection of the control panel can be done with the communications cable SC-FR PC. A connection of the control panel to a personal computer is possible

### FR-A 540 EC 0.4 k to 3.7 k

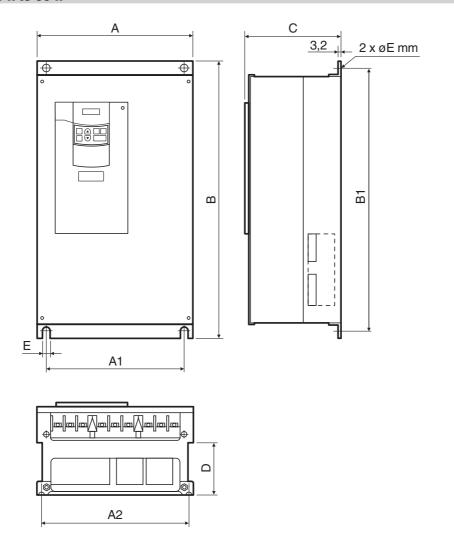


### All dimensions in mm

### FR-A 540 EC 5.5 k to 22 k



# FR-A 540 EC 30 k to 55 k

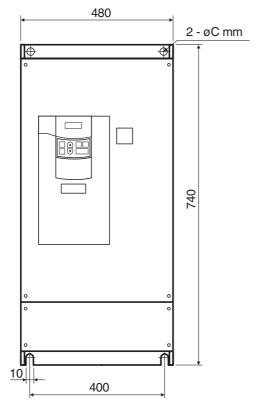


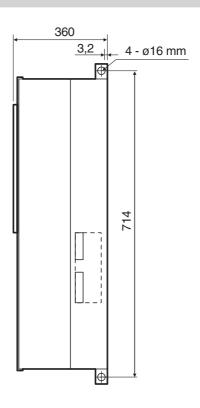
Туре	A	A1	A2	В	B1	C	D	E
FR-A 540 30 k	340	270	320	550	530	195	71.5	10
FR-A 540 37 k / 45 k / 55 k	450	380	430	550	525	250	154	12

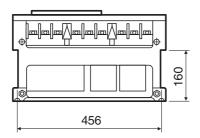


# ■ FR-A 540L-G 75 k to 110 k

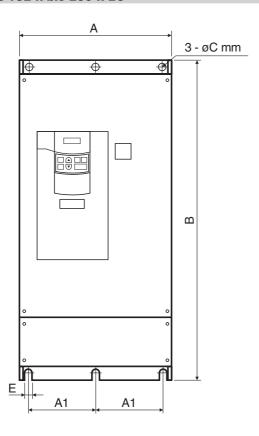


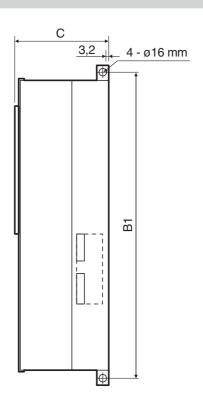


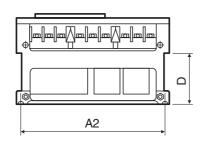




# ■ FR-A 540L-G 132 k bis 280 k EC





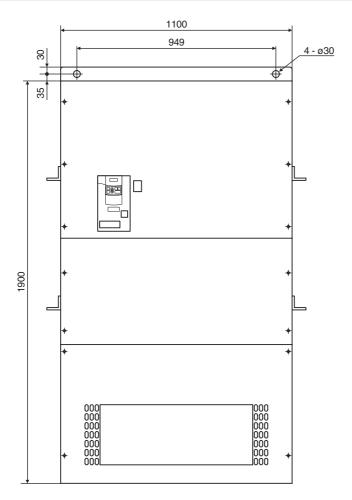


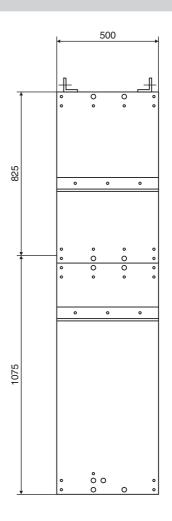
Туре	A	A1	A2	В	B1	C	D	E
FR-A 540L-G 132 k / 160 k	498	200	474	1010	984	380	185	10
FR-A 540L-G 220 k	680	300	656	1010	984	380	185	10
FR-A 540L-G 280 k	790	316	766	1330	1300	440	196	12

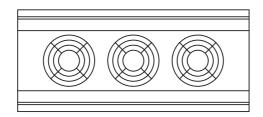




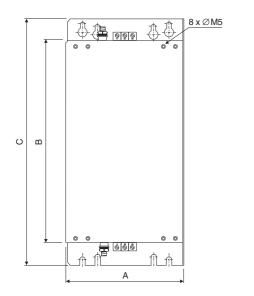
# ■ FR-A 540L-G 375 k and 450 k EC

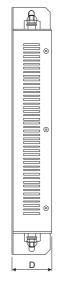


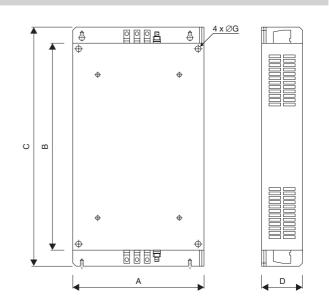




### ■ Special Noise Filters for FR-A 540 EC / FR-A 520







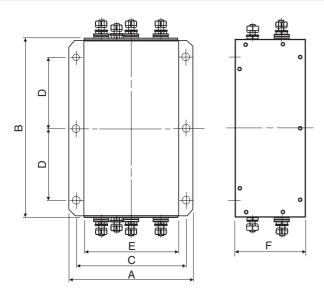
Filter	Inve	erter	A	D.	c	n	e	Weight
riitei	FR-A 540	FR-A 520	A .					[kg]
FFR-A540-8A-SF100	0.4 k-1.5 k	0.4 k/0.75 k	150	260	315	50	M5	1.5
FFR-A540-16A-SF100	2.2 k/3.7 k	1.5 k/2.2 k	150	260	315	50	M5	1.5
FFR-A540-30A-SF100	5.5 k-7.5 k	3.7 k	220	260	315	60	M5	3

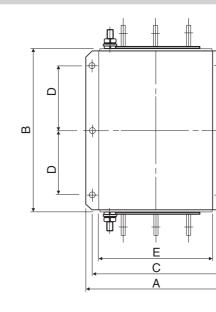
All dimensions in mm

Filter	Inve	erter	A	В	c	D	G	Weight
riitei	FR-A 540	FR-A 520	A	Ь	•	Ü	u	[kg]
FFR-A540-50A-SF100	11 k–15 k	5.5 k	251.5	400	460	80	M5/M8	3.5
FFR-A540-75A-SF100	18.5 k/22 k	7.5 k/11 k	251.5	400	476	80	M5/M8	4.1
FFR-A540-95A-SF100	30 k	15 k	340	550	626	90	M8	6.7
FFR-A540-120A-SF100	37 k	18.5 k	450	550	636	120	M10	9.7
FFR-A540-180A-SF100	45 k-55 k	22 k-30 k	450	550	652	120	M10	10.8

All dimensions in mm

# ■ Noise Filters for FR-A 540L-G EC / FR-A 520





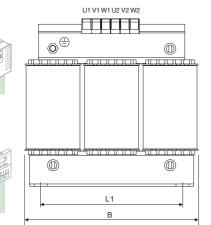


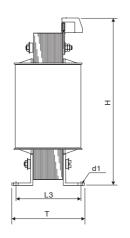
Filter	Inve	erter	۸	D	,	D			Weight
riiter	FR-A 540L-G	FR-A 520	A	D	١	ע	•	ľ	[kg]
FN 3359-180-28	75 k	37 k	210	300	185	120	160	120	6.5
FN 3359-250-28	90 k	45 k	230	300	205	120	180	125	7

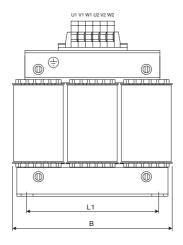
All dimensions in mm

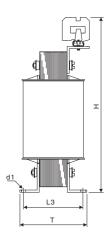
Filter	A	D	c	n	·		Weight		
riitei	FR-A 540L-G	FR-A 520	A	ь	•	U	Ė	•	[kg]
FN 3359-400-99	110 k-132 k	55 k	260	306	235	120	210	115	10.5
FN 3359-600-99	160 k/220 k	_	260	306	235	120	210	135	11
FN 3359-1000-99	280 k/375 k	_	280	356	255	145	230	170	18
FN 3359-1600-99	450 k	_	300	406	275	170	250	160	27

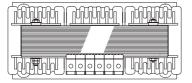
### ■ Power Chokes for Three-Phase Current FR-BAL-B-□□k

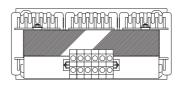












Choke	Inverter	В	T	Н	L1	L3	d1	Weight [kg]
FR-BAL-B-4.0 k	FR-A 540-0.4 k-3.7 k	125	82	130	100	56	5 x 8	3.0
FR-BAL-B-5.5 k	FR-A 540-5.5 k	155	85	145	130	55	8 x 12	3.7
FR-BAL-B-11 k	FR-A 540-11 k	155	100	150	130	70	8 x 12	5.5
FR-BAL-B-15 k	FR-A 540-15 k	190	115	210	170	79	8 x 12	10.7
FR-BAL-B-22 k	FR-A 540-18.5 k/22 k	190	115	210	170	79	8 x 12	11.2

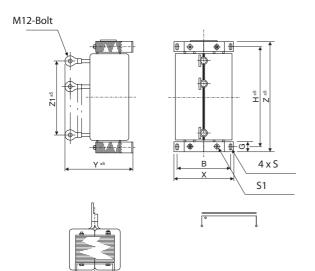
Choke	Inverter	В	T	Н	L1	L3	d1	Weight [kg]
FR-BAL-B-30 k	FR-A 540-30 k	190	118	230	170	79	8 x 12	3.0
FR-BAL-B-37 k	FR-A 540-37 k	210	128	265	175	97	8 x 12	3.7
FR-BAL-B-45 k	FR-A 540-45 k	230	165	280	180	122	8 x 12	5.5
FR-BAL-B-55 k	FR-A 540-55 k	240	140	305	190	97	11 x 12	10.7

All dimensions in mm



Pr.DI

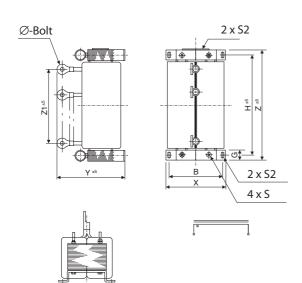
# ■ Converter Chokes for Frequency Inverters FR-A 540L-G 75 k-110 k



Inverter	X	Y	Z	Z1	В	Н	G	s	<b>S</b> 1	Ø	Weight [kg]
FR-A 540L-G 75 k	140	170	320	230	130	295	25	M6	M6	M10	14
FR-A 540L-G 90 k	150	175	337	265	130	310	25	M6	M6	M12	18
FR-A 540L-G 110 k	150	180	337	255	130	310	25	M6	M6	M12	19



# ■ Converter Chokes for Frequency Inverters FR-A 540L-G 132 k-220 k

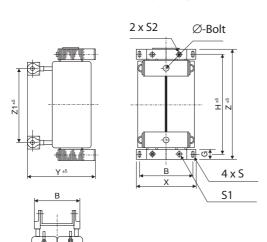


Inverter	X	Y	Z	Z1	В	Н	G	S	<b>S</b> 1	S2	Ø	Weight [kg]
FR-A 540L-G 132 k	175	225	400	285	150	365	32	M8	M6	_	M12	29
FR-A 540L-G 160 k	190	225	438	305	165	400	38	M8	M8	M8	M12	36
FR-A 540L-G 220 k	210	235	495	350	185	450	44	M10	M8	M8	M12	48

All dimensions in mm



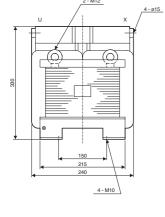
# ■ Converter Choke for Frequency Inverters FR-A 540L-G 280 k

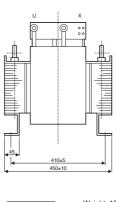


Inverter	X	Y	Z	<b>Z</b> 1	В	н	G	S	S1	S2	Ø	Weight [kg]
FR-A 540L-G 280 k	220	250	495	380	195	450	44	M10	M8	M8	M16	57

# ■ Converter Choke for Frequency Inverters FR-A 540L-G 375 k und 450 k



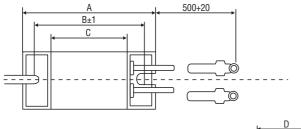


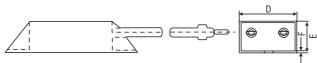


Weight: 100 kg

### **■** External Brake Resistor FR-ABR-H□□k





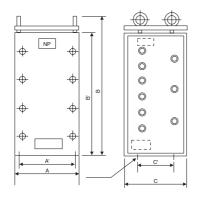


Brake resistor	A	В	c	D	E	F	Weight [kg]
FR-ABR-H0,4 k	115	100	75	40	20	2,5	0,2
FR-ABR-H0,75 k	140	125	100	40	20	2,5	0,2
FR-ABR-H1,5 k	215	200	175	40	20	2,5	0,4
FR-ABR-H2,2 k	240	225	200	50	25	2,0	0,5
FR-ABR-H3,7 k	215	200	175	60	30	2,5	0,8
FR-ABR-H5,5 k	335	320	2/95	60	30	2,5	1,3
FR-ABR-H7,5 k	400	385	360	80	40	2,5	2,2

All dimensions in mm



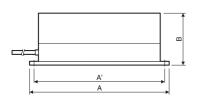
### **■** External Brake Resistor MT-BR5-H75 k

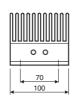


Brake resistor	A	A'	В	B'	C	C'	Weight[kg]
MT-BR5-H75 k	510	480	885	800	465	300	70

All dimensions in mm

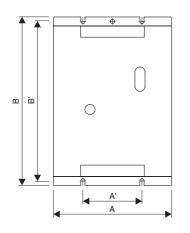
### **■** External Brake Resistor RUFC

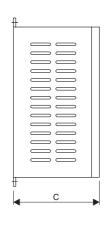




Brake resistor	A	A'	В	Weight[kg]
RUFC15	245	230	75	4,0
RUFC22	310	295	75	4,7
RUFC40	365	350	75	9,4
RUFC110	365	350	75	18,8

# **■** Brake Unit BU-H





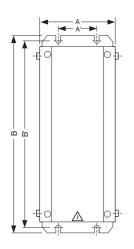
Brake unit	A	A'	В	B'	C	Weight[kg]
BU-H15 k	160	90	240	225	145	3,2
BU-H30 k	160	90	240	225	145	3,2

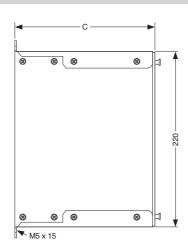






# **■** Brake Unit BU-UFS



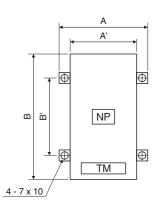


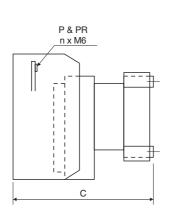
Brake unit	A	A'	В	B'	C	Weight[kg]
BU-UFS22	100	50	250	240	175	2,5
BU-UFS40	100	50	250	240	175	2,5
BU-UFS110	107	50	250	240	195	3,9

All dimensions in mm



### **■** Brake Unit MT-BU5





Brake unit	A	A'	В	B'	C	Weight[kg]
MT-BU5-H75K	118	90	200	100	256,5	1,5
MT-BU5-H150K	188	160	200	100	256,5	3,0
MT-BU5-H220K	258	230	200	100	256,5	4,5
MT-BU5-H280K	328	300	200	100	256,5	6,0
MT-BU5-H375K	398	370	200	100	256,5	7,5



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Order de Pos.	daration Number	Item (type)	Article number	Description	Remarks	
1 03.	Number	item (type)	Article liulibei	Description	Helilaiks	

Notes when ordering:

When ordering, please use only the type designations and order numbers shown in this catalogue.

A	M
Application examples	Maintenance
	Optional control panel FR-PU04
В	
Block diagram	<b>N</b> Noise filters
Dimensions	Description
Dimensions	0
	Operating condtions
C	Operating modes
Communications possibilities	Operation
Control units	Options
Description FR-DU04	
Dimensions	P
Chokes	Parameters
D	Description         28           Dimensions         38
Dimensions	Power supply
Brake resistors/units	Control circuit
Control units	Frequency inverter
Chokes	Protective functions
Frequency inverters FR-A 540L-G EC	
Noise filters	R
	RESET function
E	nesetting methode after failure
EMC compliance	
Environmental conditions	<b>S</b>
Error display	Sample applications
Description	Signal terminals
Dimensions	Soft-PWM Function
External options	Software
F	Brake resistors
FR-DU04	Chokes
FR-PU04	Frequency inverter
Frequency inverter	Noise filters
Dimensions         32           Specifications         8	Options         25           Speed/torque characteristics         5
Functions	System description
Inverter8	
Parameter	Т
	Terminal assignment
н	Control units
Handling	Frequency inverters
Control units	Termial designation
I	V
Internal options	VFD setup software

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